Hash Table

CS143: lecture 15

Turning any value into an integer

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 - Hash functions should run in O(1) time
- There are good/bad choices for hash functions

Example: 2-letter word dictionary

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ah: used to express delight, relief, regret, or contempt

as: to the same degree or amount

at: used as a function word to indicate presence or occurrence in, on, or near

do: to bring to pass

go: to move on a course

ha: used especially to express surprise, joy, or triumph

he: that male one who is neither speaker nor hearer

hi: used especially as a greeting

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What hash function could we use to map keys to ints?

а	b	С	d	е	f	g	h	i	j	k	I	m	n	0	р	q	r	S	t	u	V	W	X	у	Z
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25

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How many 2-letter words are there?

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- How to map words into [0, 676)?

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0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25

- $hash(\alpha\beta) = 26\alpha + \beta$
- $hash(go) = 26 \cdot 6 + 14 = 170$

Example: 2-letter word dictionary

Example!

Hashing Problem

Word	Letters
Longest chemical	189,819
Longest word in Merriam-Webster	45
Supercalifragilisticexpialidocious	34
Longest word in Shakespeare's works	27

Problem

Can we extend this function to work for all words?

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- Too big for an array!
- Also, English has ~700,000 words; we only need a tiny fraction of these.
- Solution: Compress

Hashing Compression

Compression

Generally, hash functions do not care about its output range.

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- We use a compression function to put the integer in the reasonable range [0,size)
- Common choice: modulus
 - a % b calculates the remainder of a divided by b
 - a % b always returns an int in the range [0, b)

Compression example

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

Compression example

Keys: integer

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

Compression example

Keys: integer

• Table size: 10

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

Compression example

Keys: integer

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hash: itself

0	
1	
2	
3	
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5	
6	
7	
8	
9	

Compression example

Keys: integer

• Table size: 10

hash: itself

• compress: hash % 10

0	
1	
2	
3	
4	
5	
6	
7	
8	
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Compression example

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Table size: 10

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0	
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Table size: 10

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0	
1	
2	
3	
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Keys: integer

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0	
1	
2	
3	
4	
5	
6	
7	7
8	18
9	

Compression example

Keys: integer

Table size: 10

hash: itself

• compress: hash % 10

0	
1	41
2	
3	
4	
5	
6	
7	7
8	18
9	

Compression example

Keys: integer

Table size: 10

hash: itself

• compress: hash % 10

• insert: 7, 18, 41, 35

•

0	
1	41
2	
3	
4	
5	35
6	
7	7
8	18
9	

Compression example

- Keys: integer
- Table size: 10
- hash: itself
- compress: hash % 10
- insert: 7, 18, 41, 35
- What if we try to insert 75?

0	
1	41
2	
3	
4	
5	35
6	
7	7
8	18
9	

Compression example

Keys: integer

• Table size: 10

hash: itself

• compress: hash % 10

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• What if we try to insert 75?

0	
1	41
2	
3	
4	
5	35
6	
7	7
8	18
9	

75

Hashing Collision

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 - Compression merges different hashes together
- All tables need to handle collision

Hashing Handling Collision

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- 2. When they arise (inevitably):
 - 1. Have a way to put collisions in a table.

Picking a good hash function

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Minimize collision:

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 - hash(k) = 1
 - What is the best possible hash function?
 - Every input maps to a distinct output, $f(x) = f(y) \implies x = y$
 - This is called perfect hashing. The two-letter hash function is a perfect hash function.

Picking a good hash function (Example)

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- CS284: Cryptography

Recap

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- We need to handle collisions:
 - Collisions can be the result of the hash function
 - of compression

Handling Collision

Handling Collision

Two approaches:

Handling Collision

- Two approaches:
 - 1. Chaining

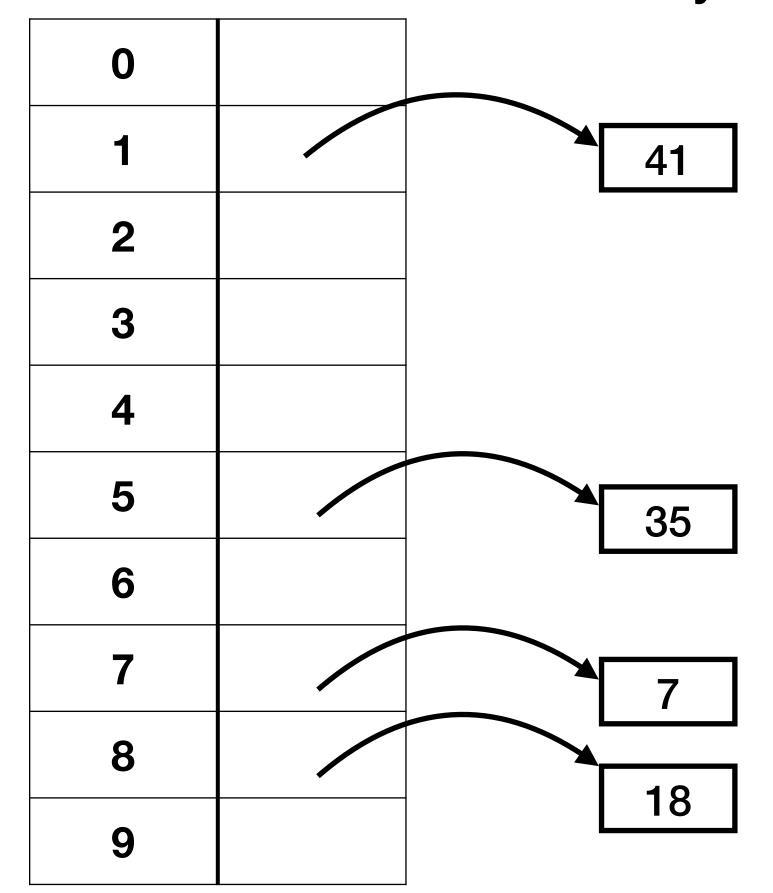
Handling Collision

- Two approaches:
 - 1. Chaining
 - 2. Probing

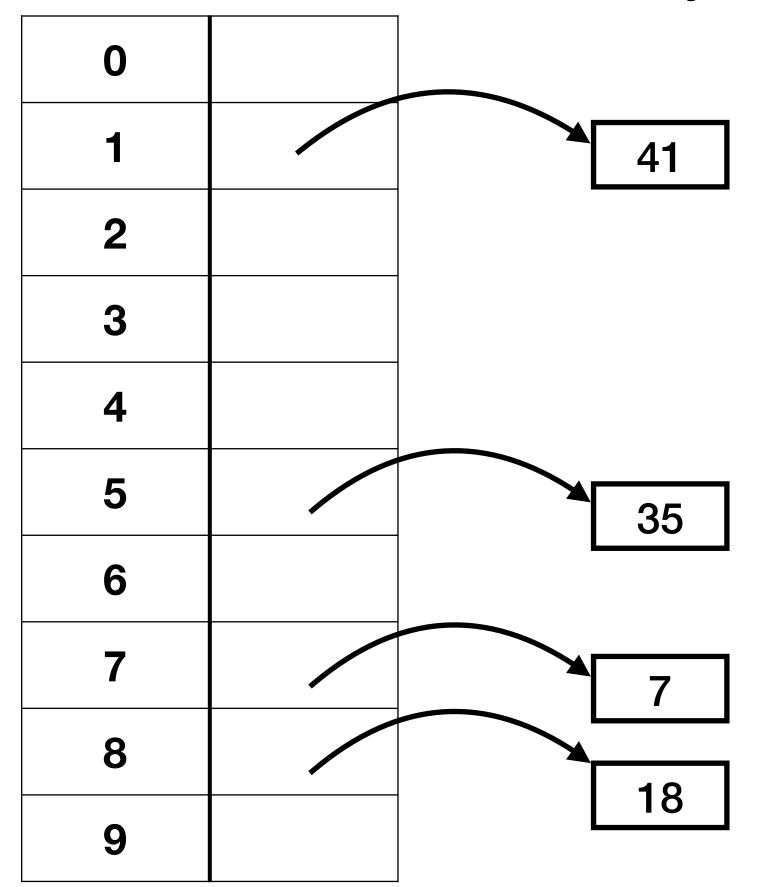
• Each slot is a *list* of key-value pairs, called a *bucket*

0	
1	41
2	
3	
4	
5	35
6	
7	7
8	18
9	

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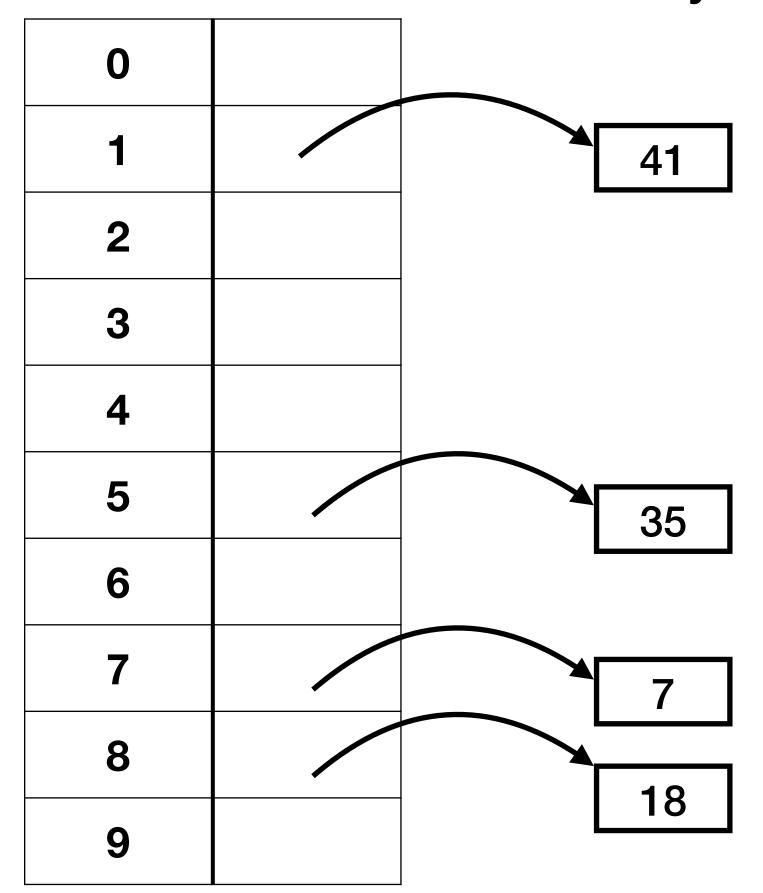


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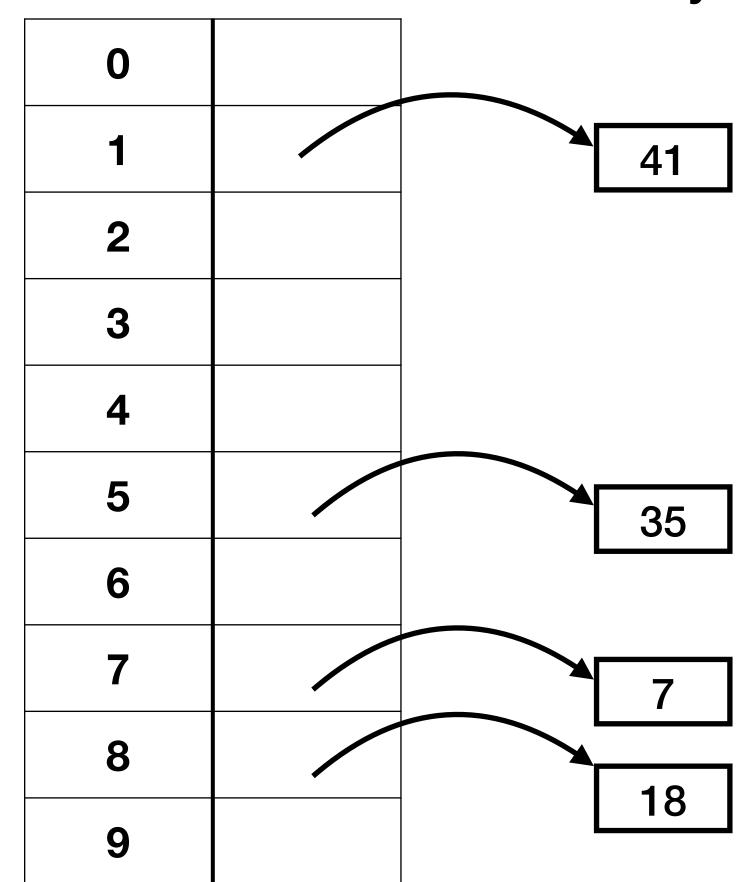
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- You can use either list implementation
 - ...but there is an obvious choice

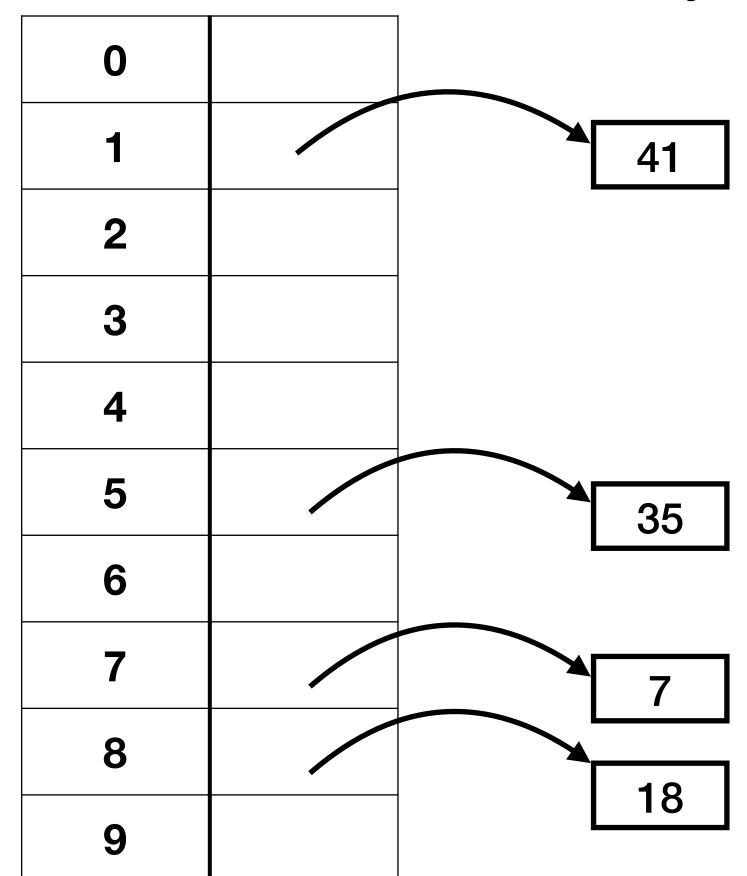
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- You can use either list implementation
 - ...but there is an obvious choice
 - linked list, because of deletion

Insert

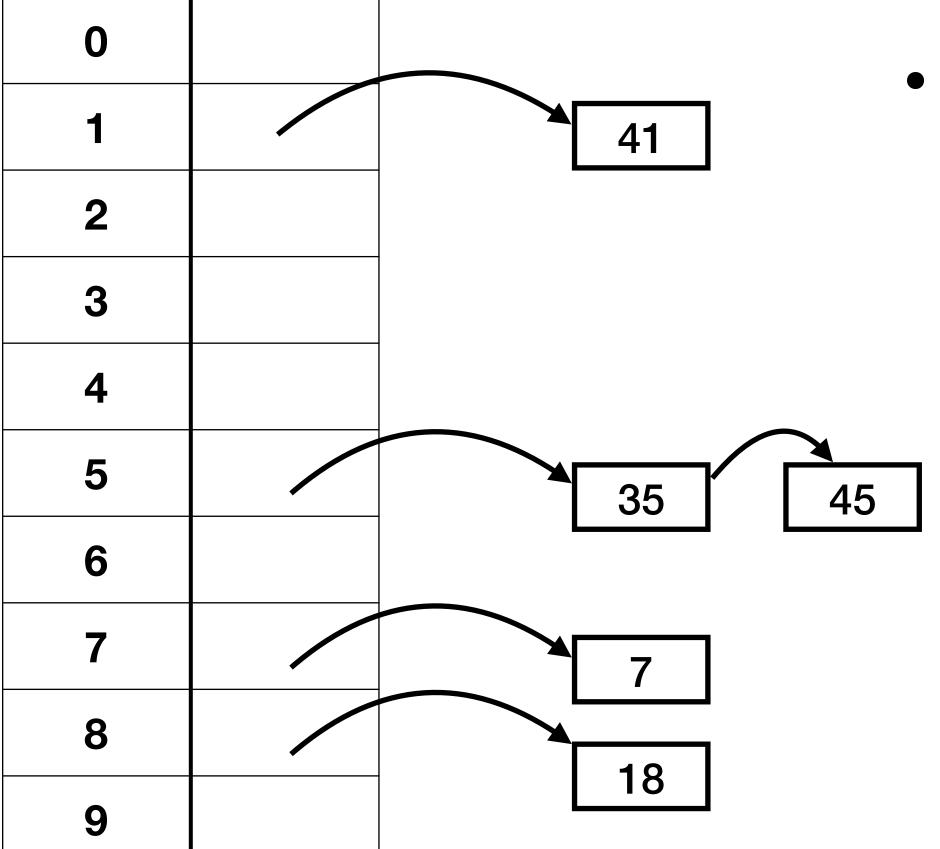
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Collisions will be prepended into the list

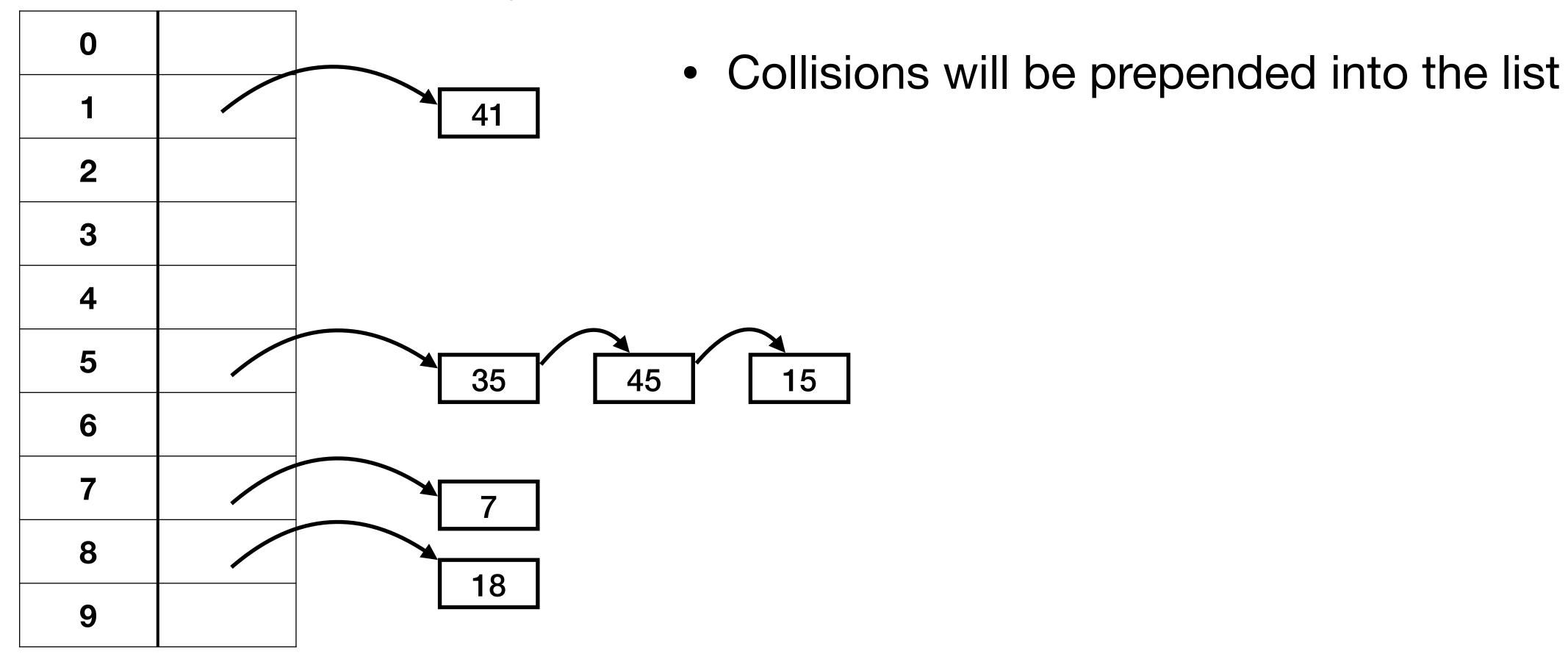
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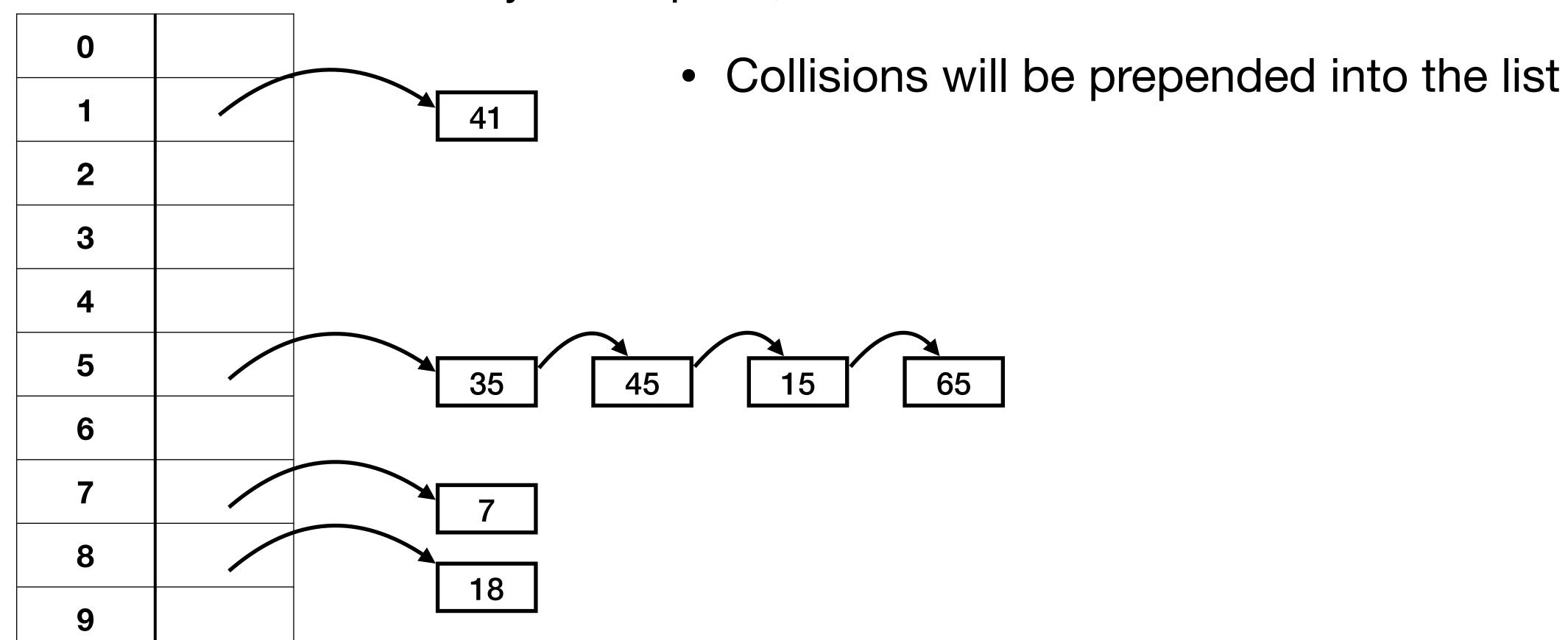


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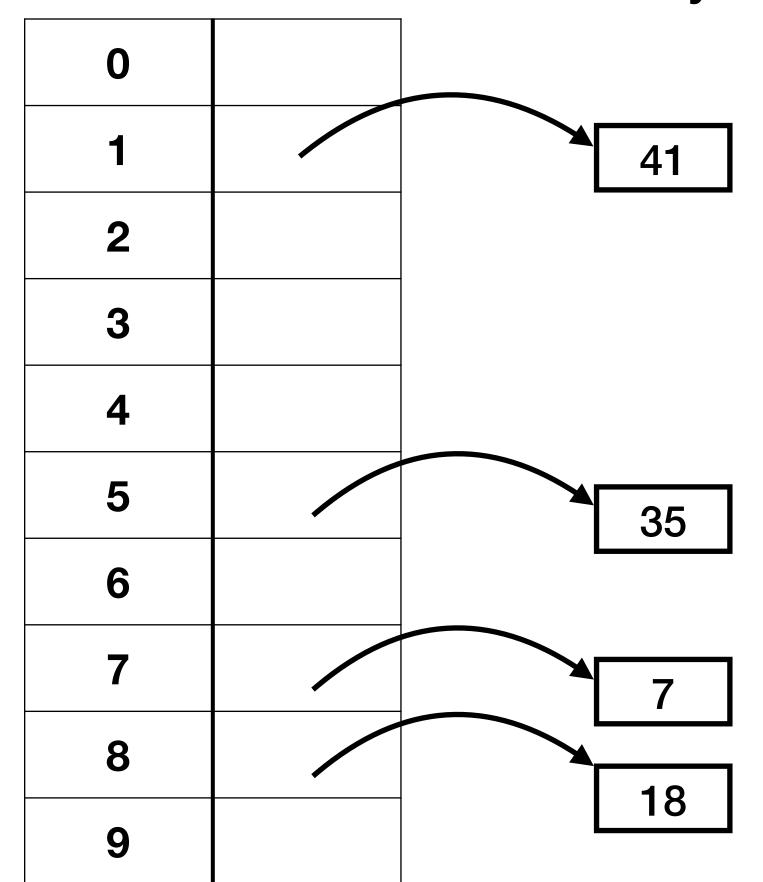
Insert



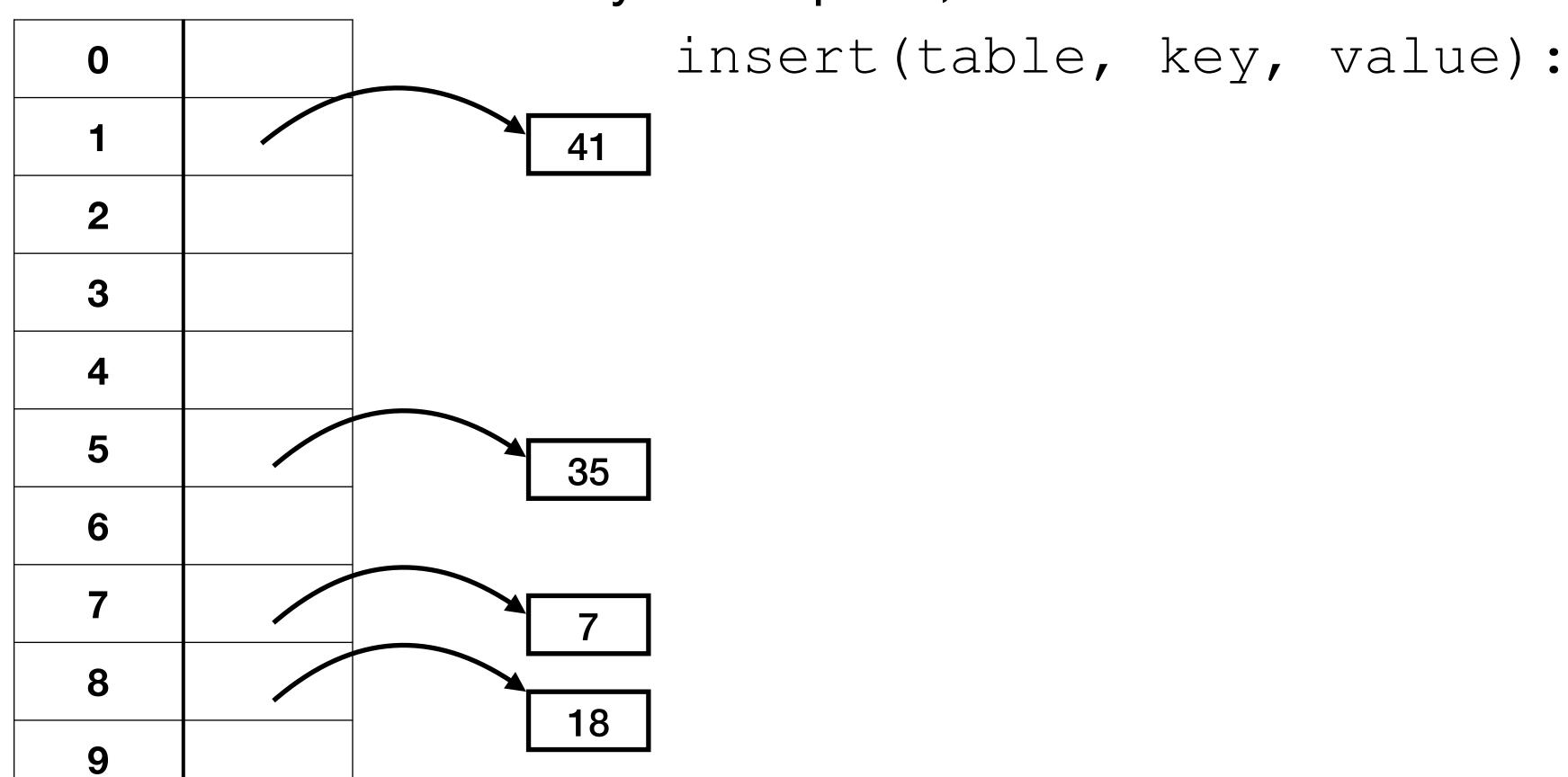
Insert



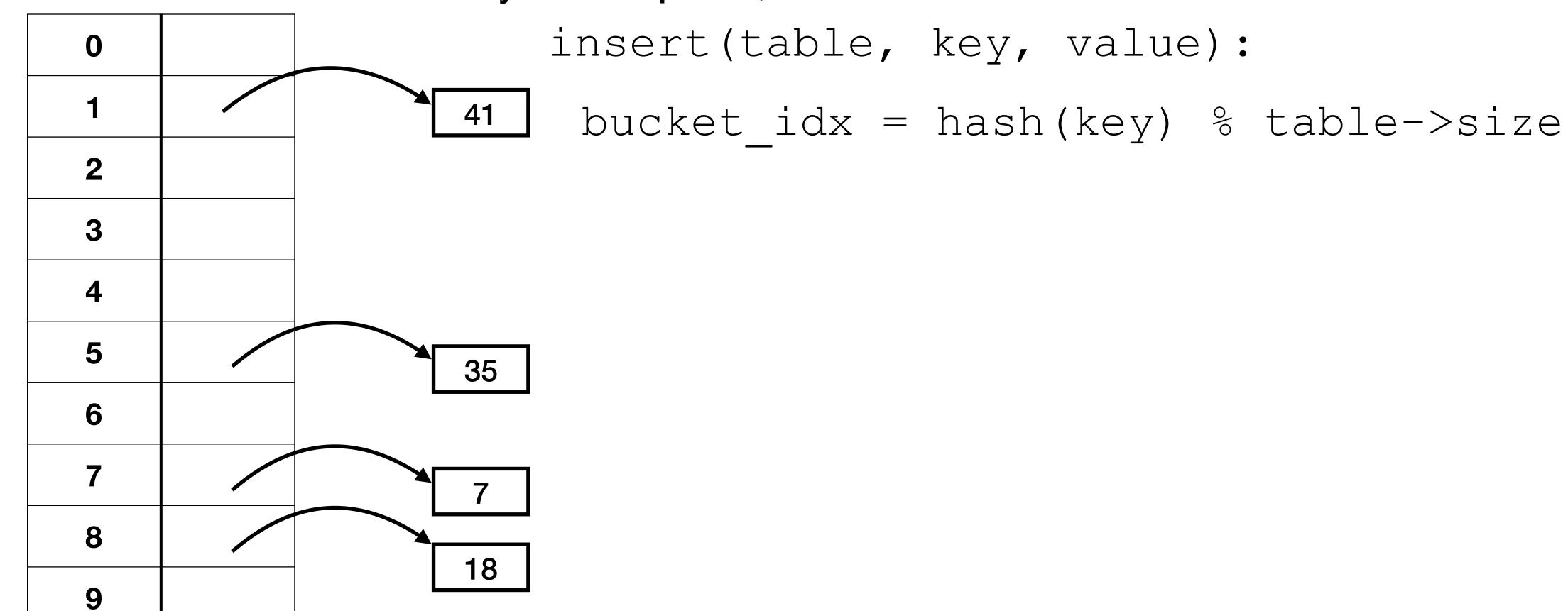
Insert



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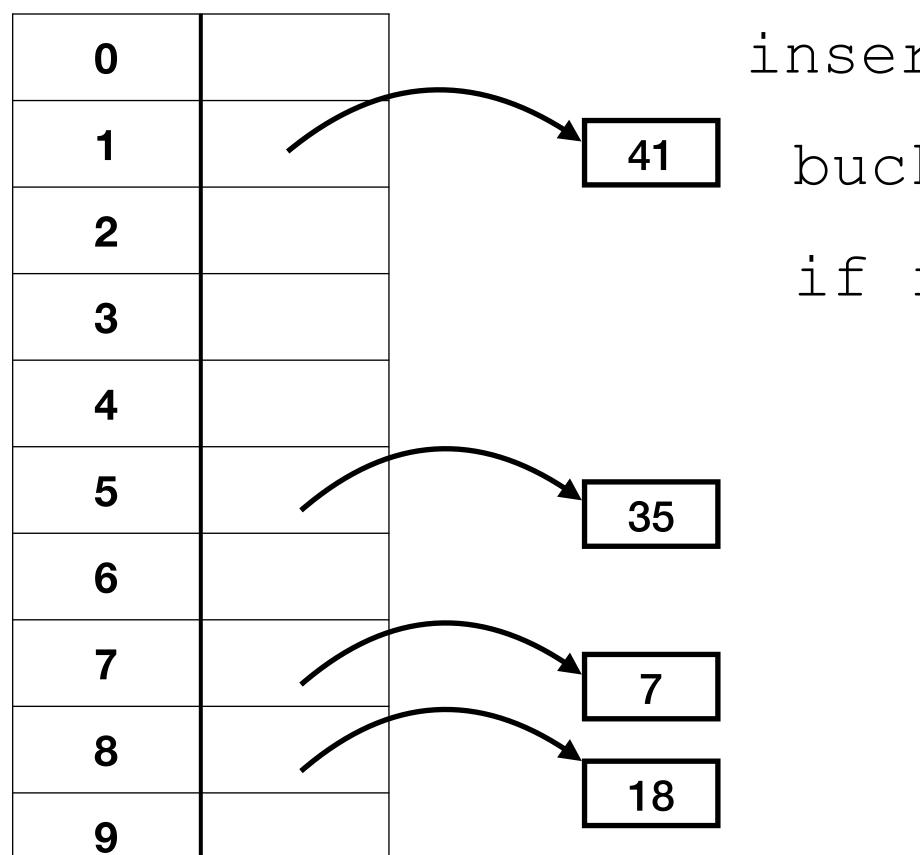


Insert



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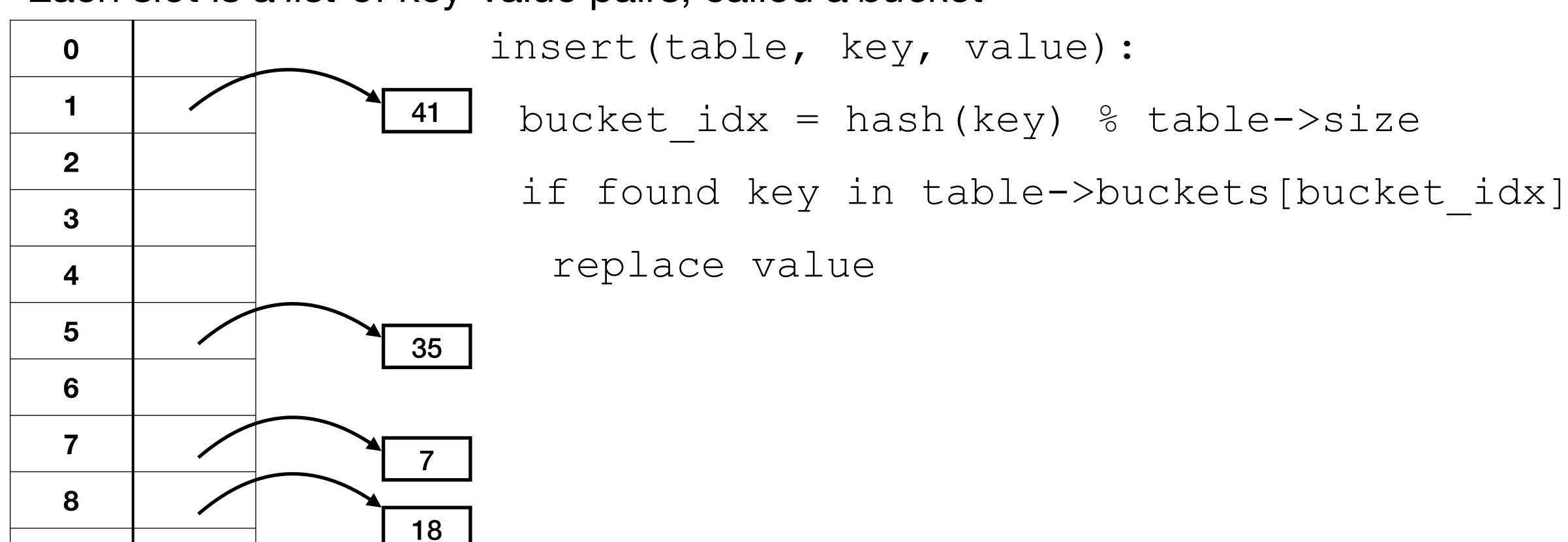
insert(table, key, value):

bucket_idx = hash(key) % table->size

if found key in table->buckets[bucket_idx]

Insert

9

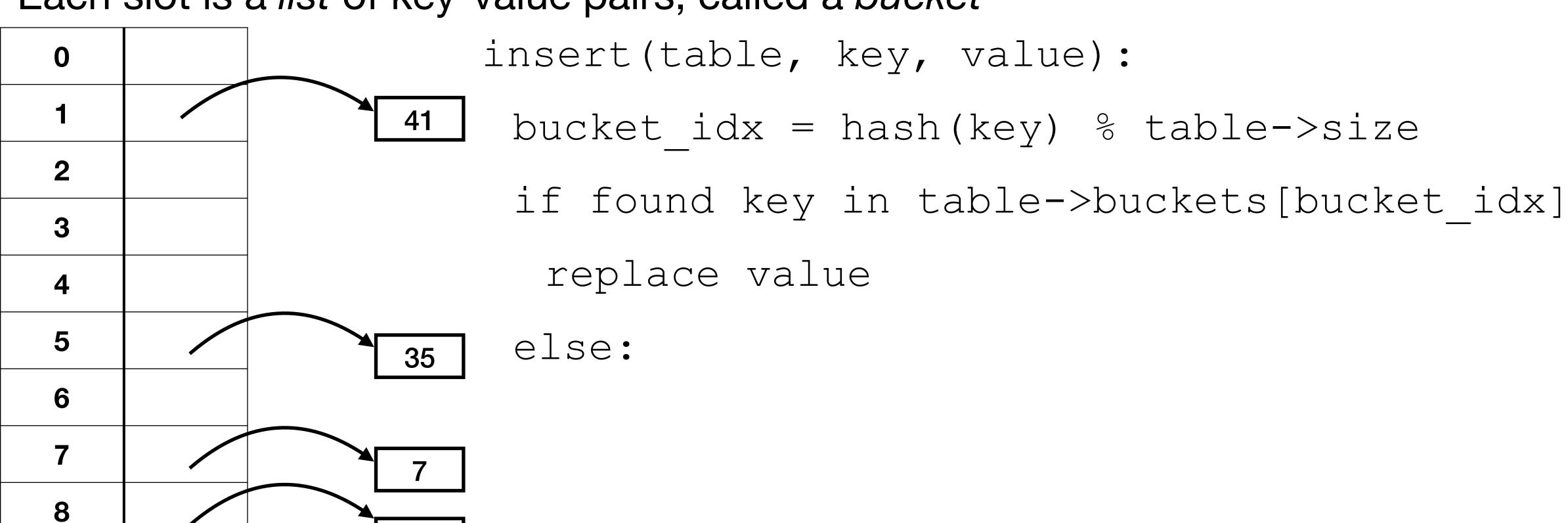


Insert

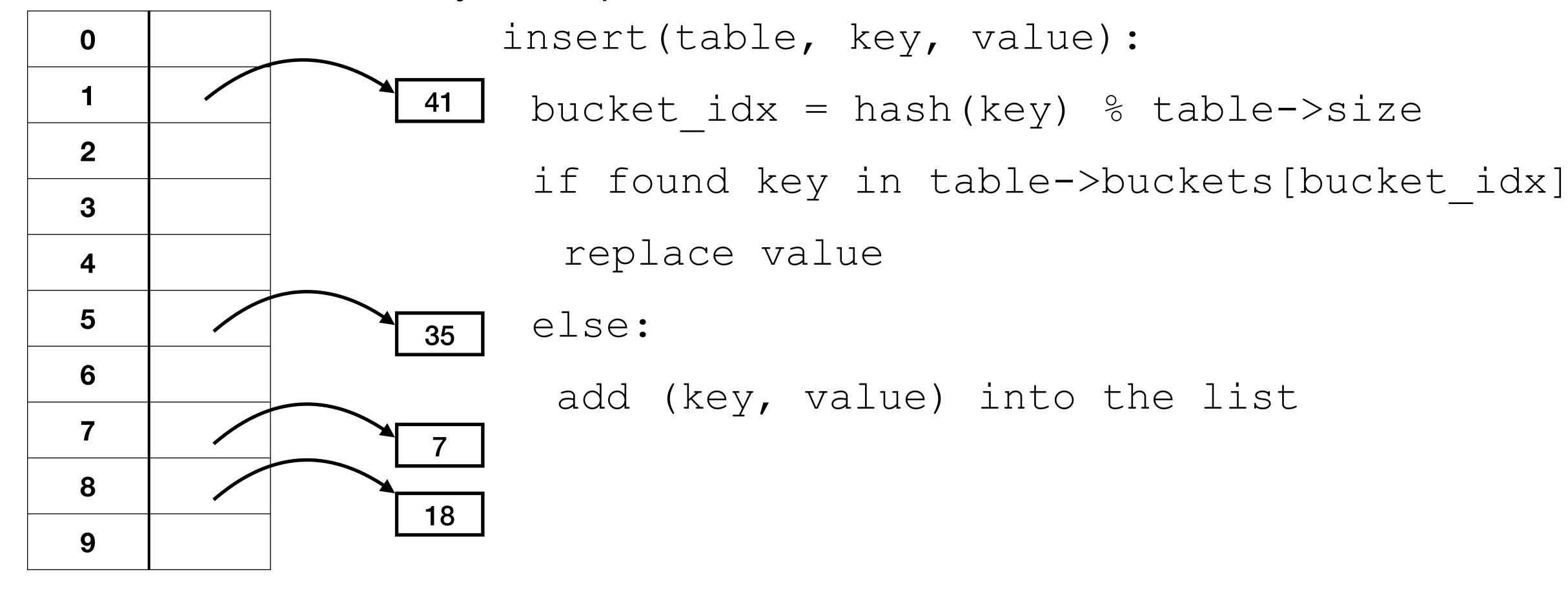
9

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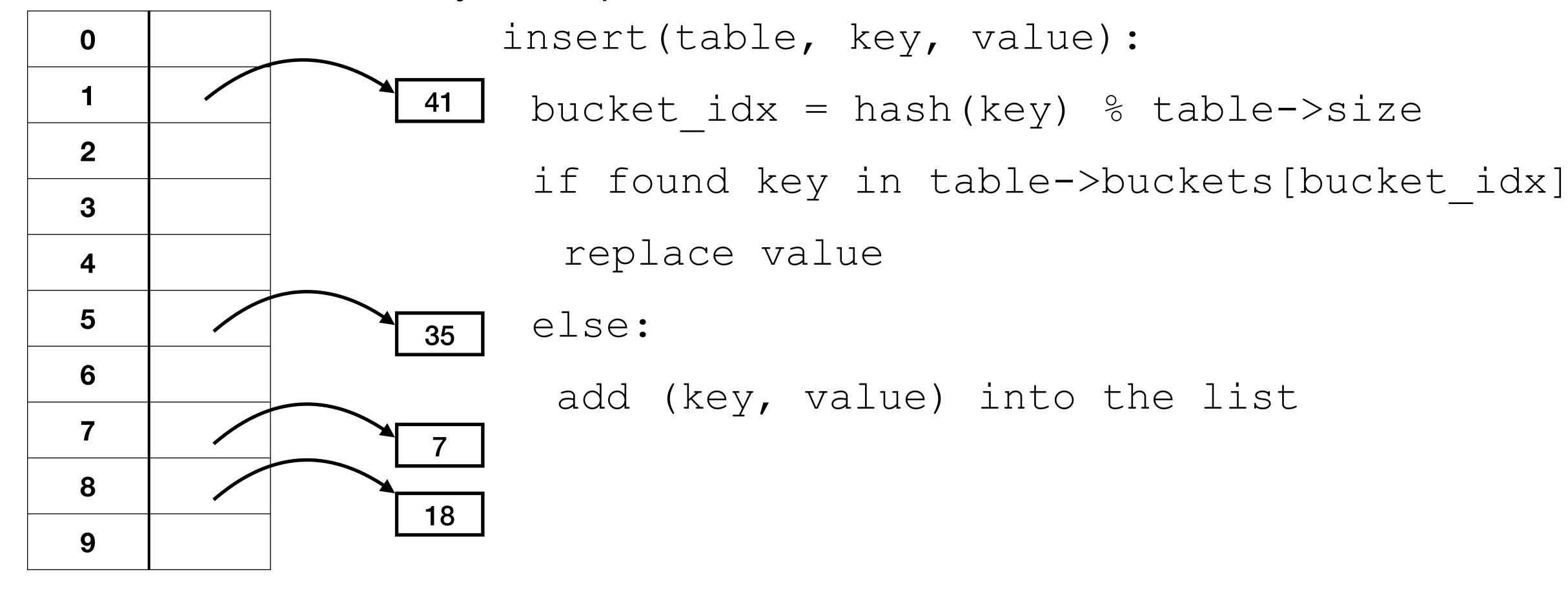
18



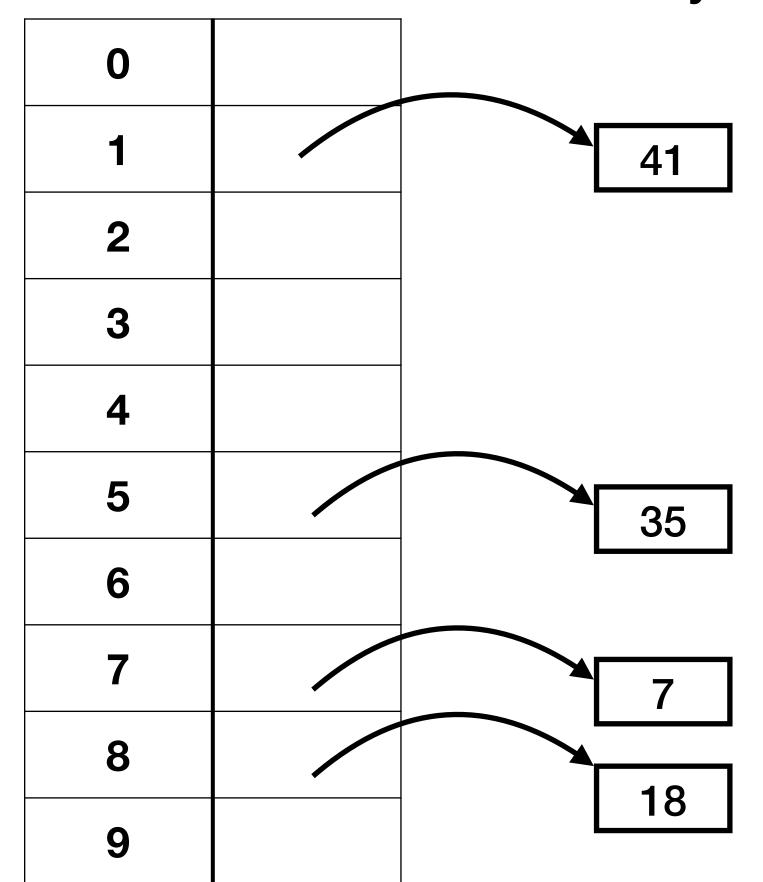
Insert



Insert

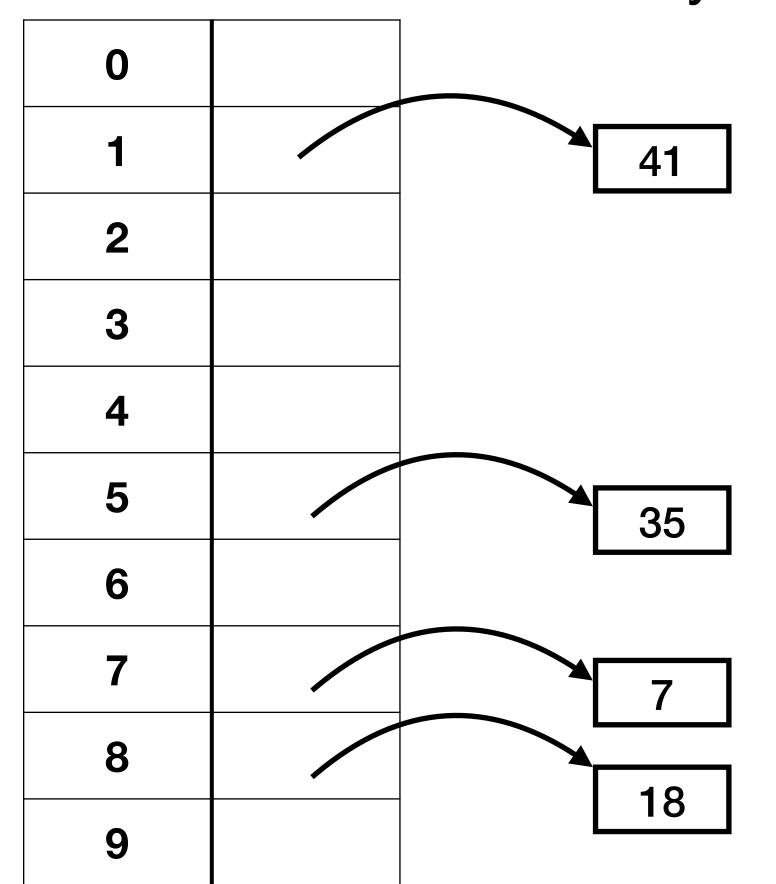


Insert



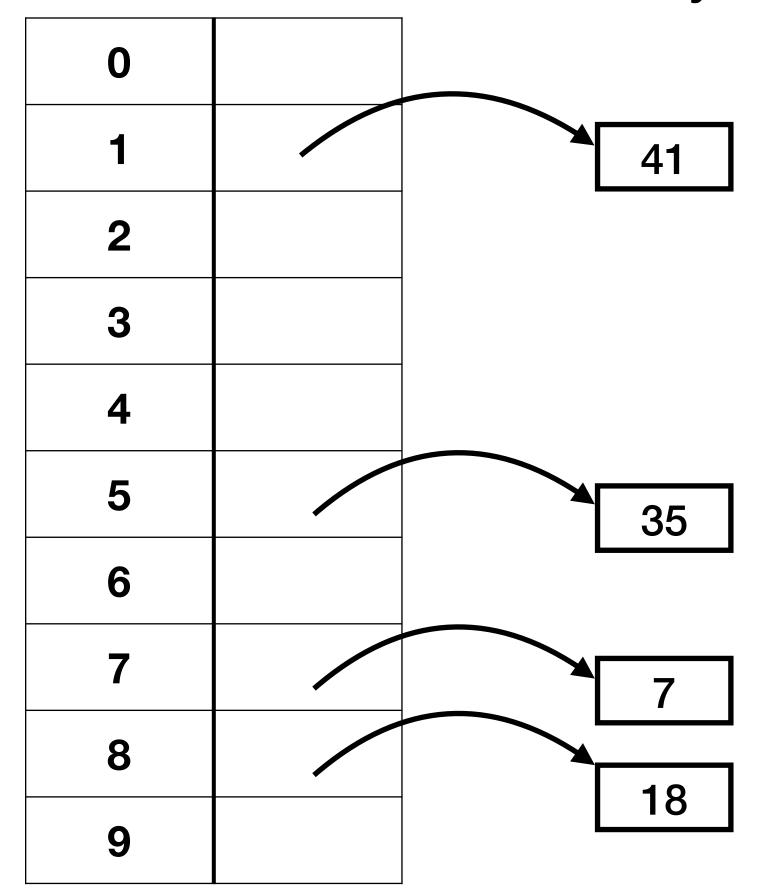
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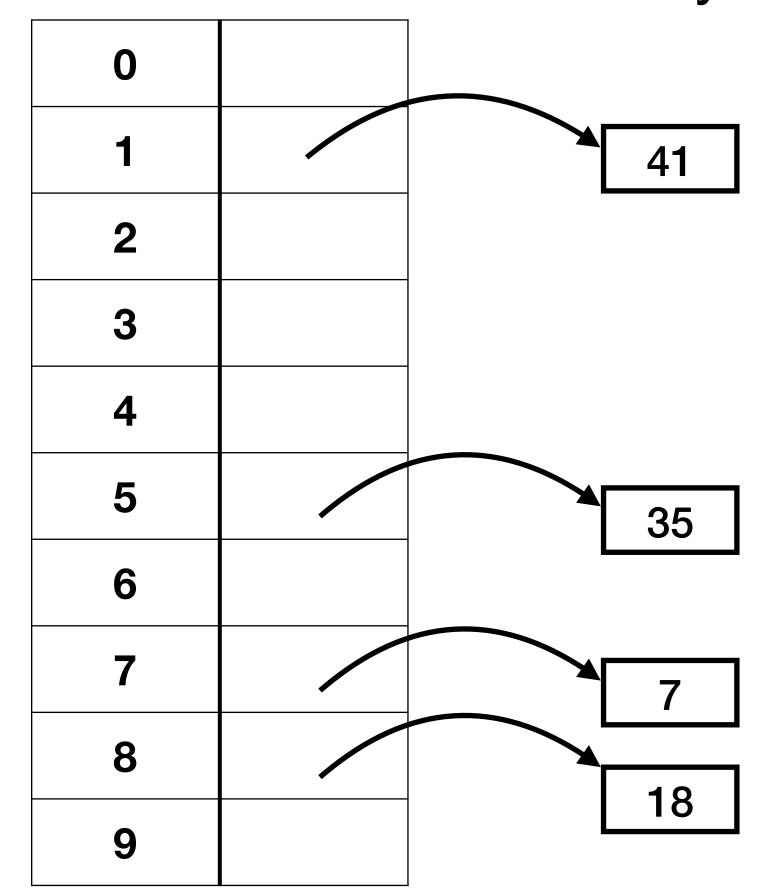
struct table {

Insert



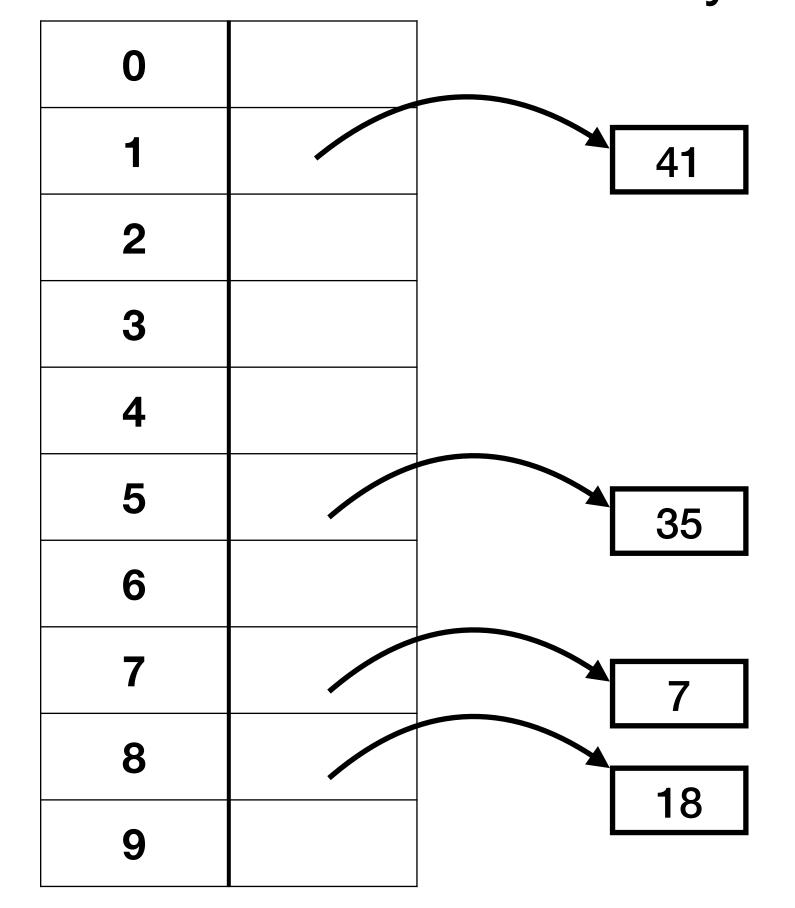
```
struct table {
   int size;
```

Insert



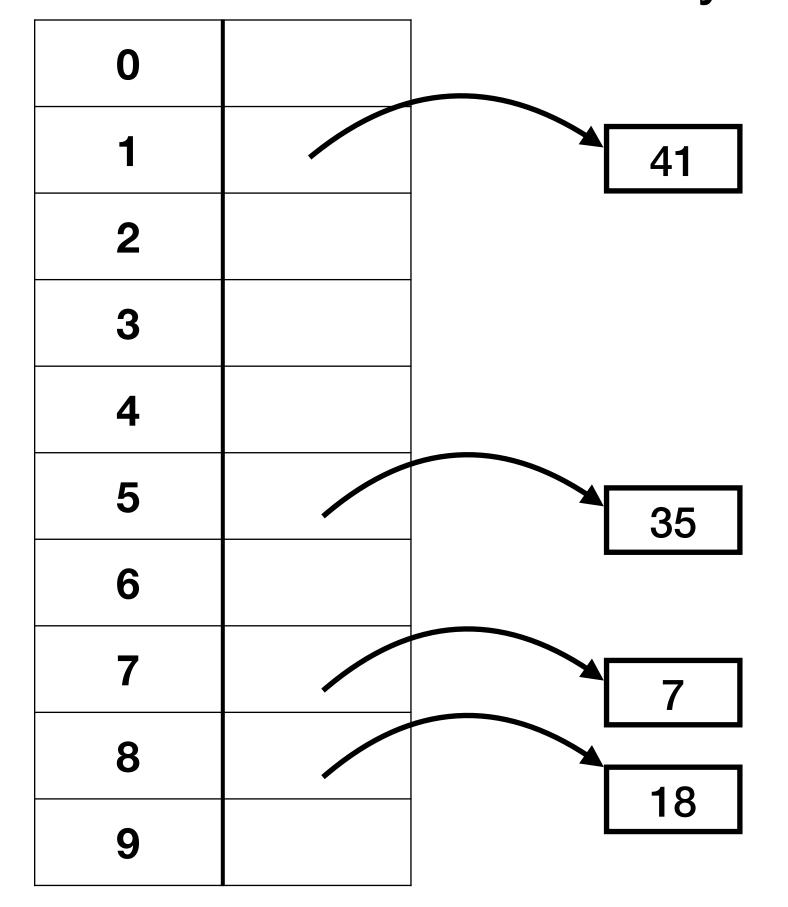
```
struct table {
   int size;
   int length;
```

Insert



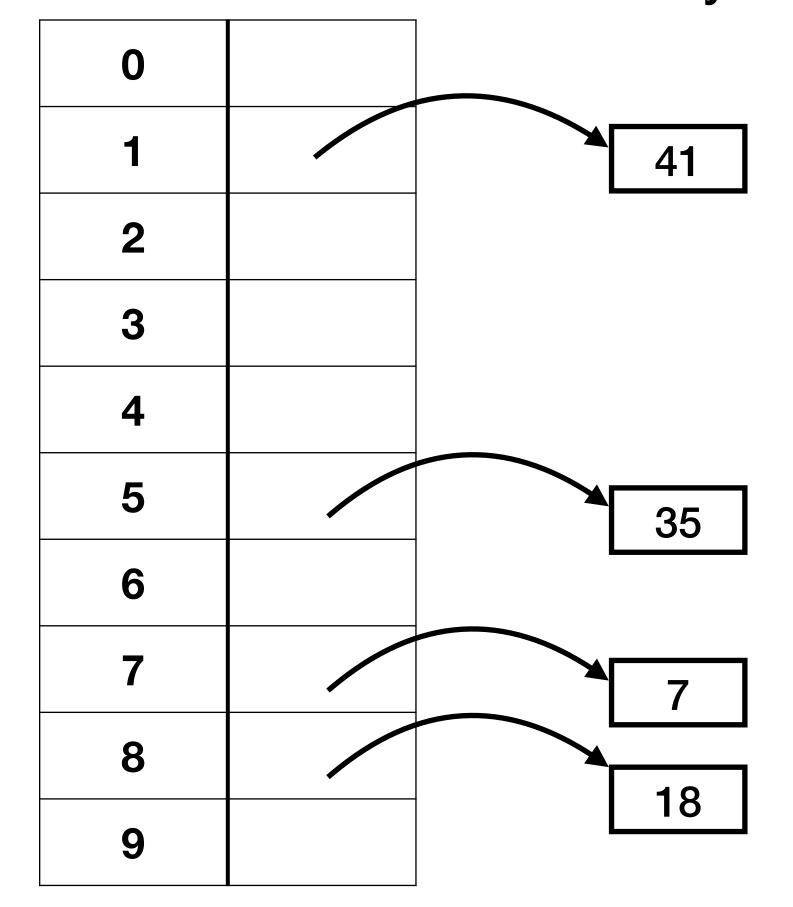
```
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   int size;
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   int (*eq)(void *, void *);
```

Insert



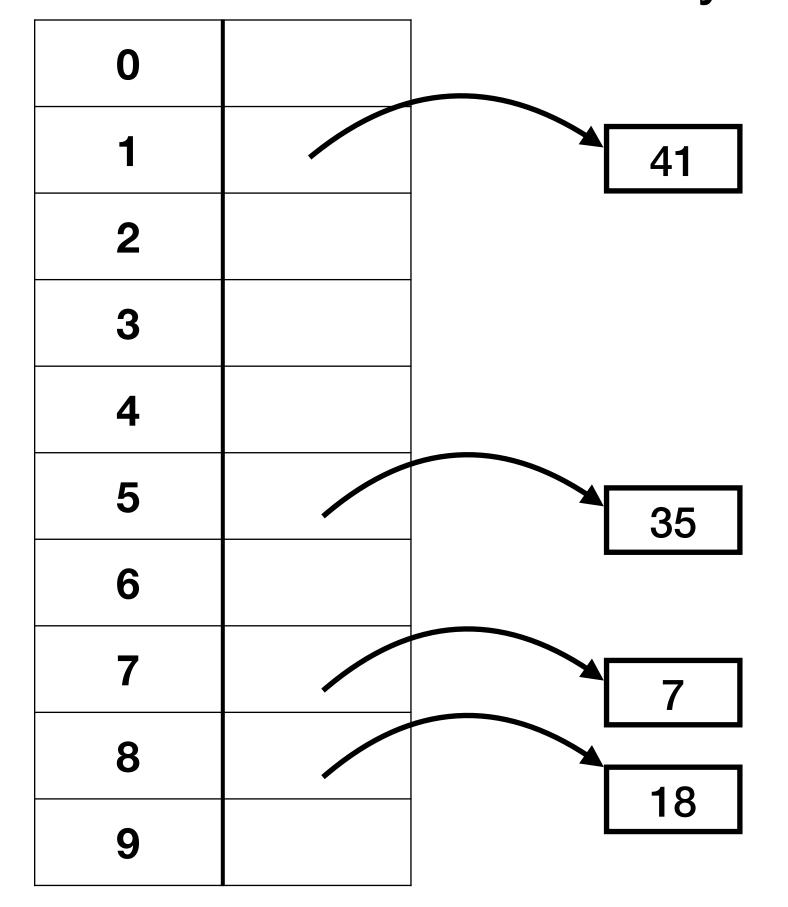
```
struct table {
   int size;
   int length;
   int (*eq)(void *, void *);
   uint64_t (*hash)(void *);
```

Insert



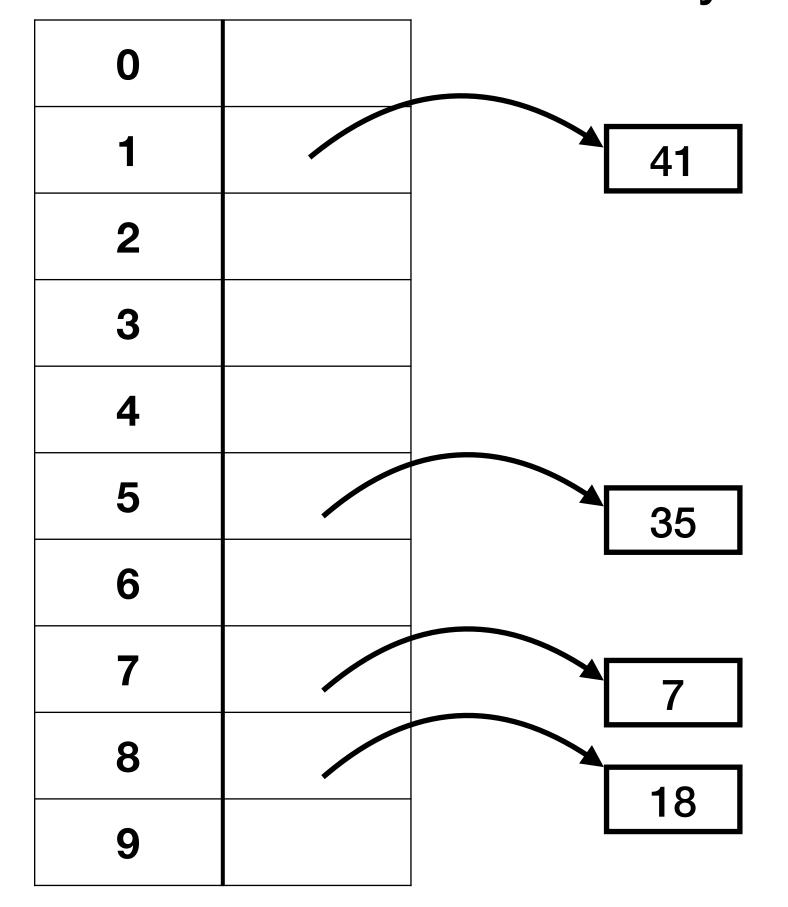
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struct table {
   int size;
   int length;
   int (*eq) (void *, void *);
   uint64_t (*hash) (void *);
   struct bucket *buckets[];
```

Insert



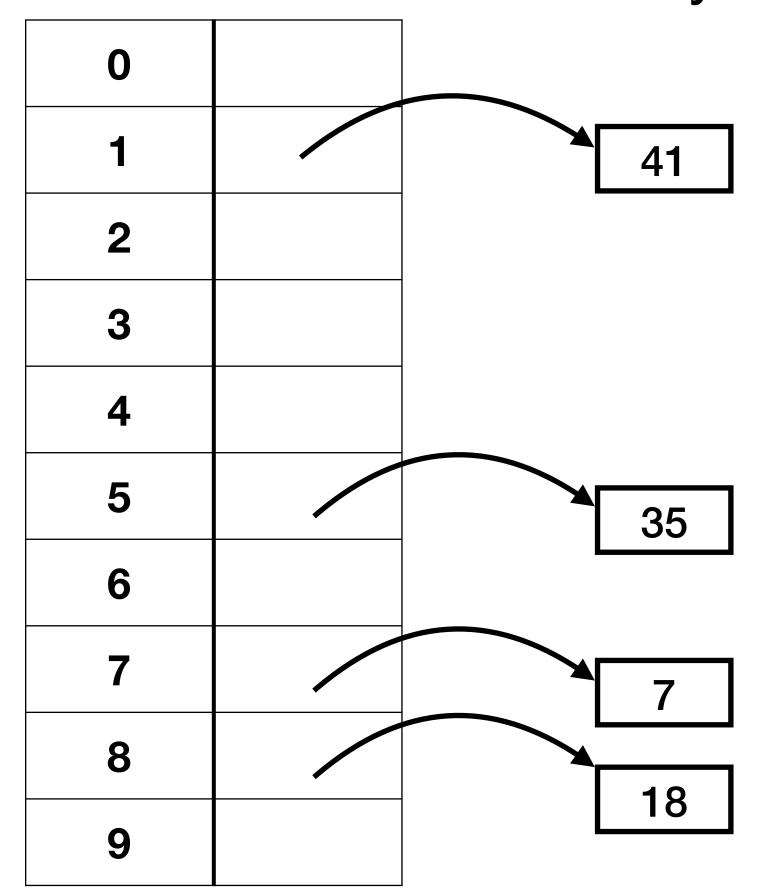
```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[];
};
```

Insert



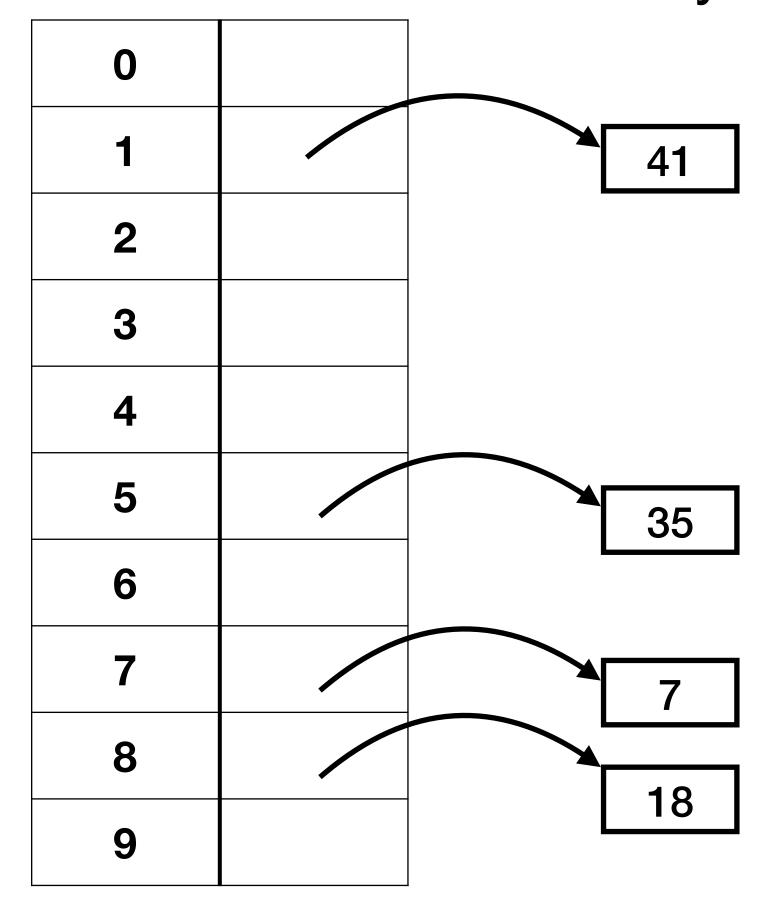
```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[];
};
```

Insert



```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[];
};
```

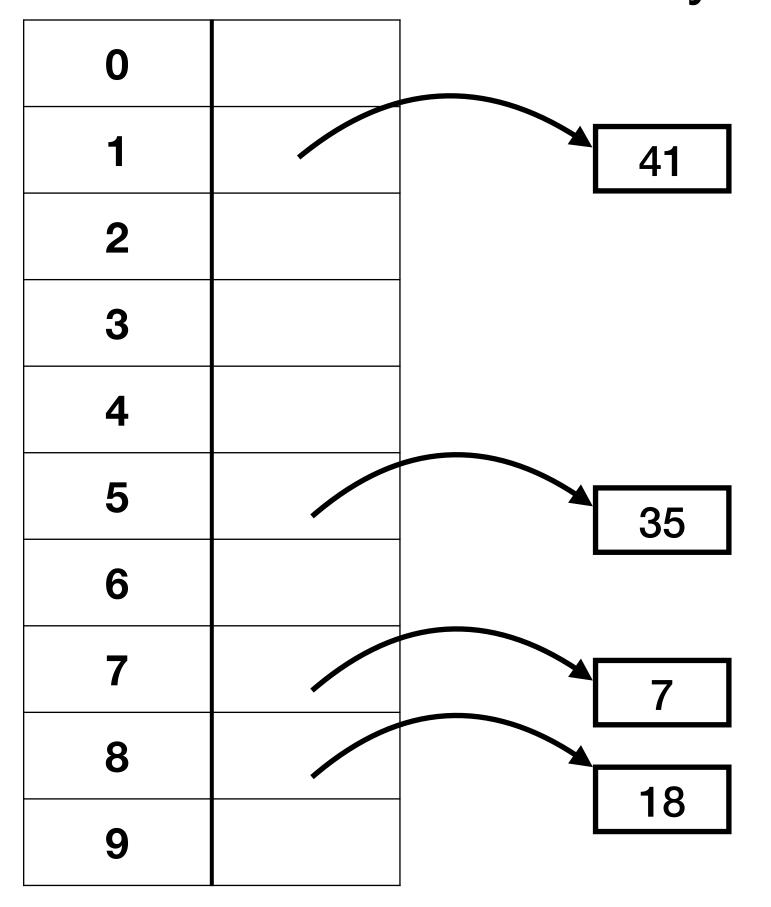
Insert



```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[];
};

struct bucket {
    void *key;
```

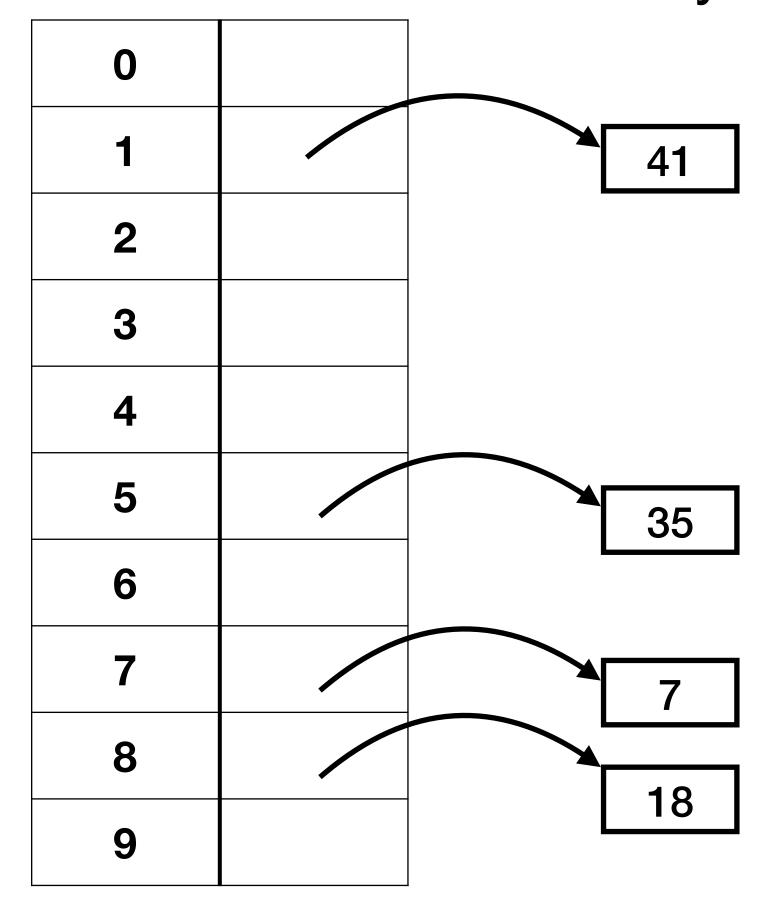
Insert



```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[];
};

struct bucket {
    void *key;
    void *value;
```

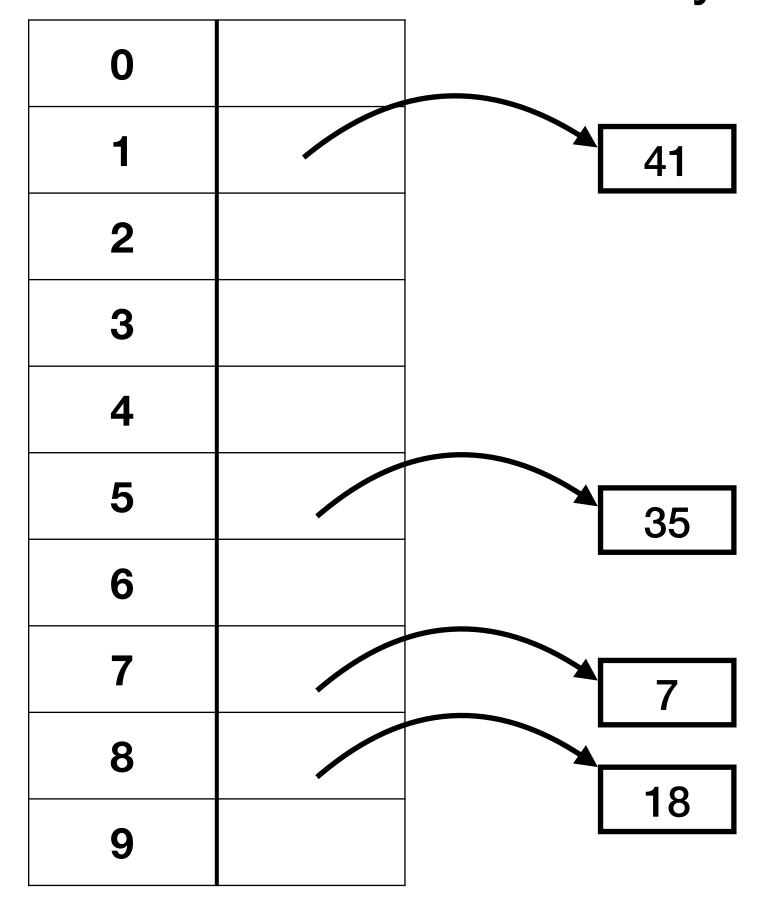
Insert



```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[];
};

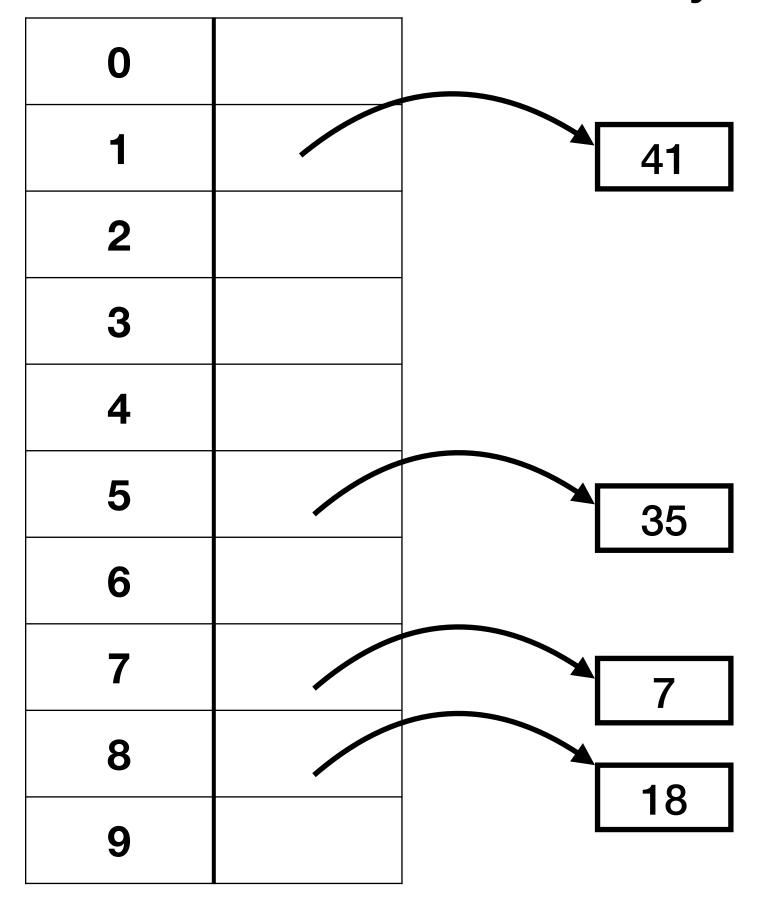
struct bucket {
    void *key;
    void *value;
    struct bucket *next;
```

Insert



```
struct table {
        int size;
        int length;
        int (*eq) (void *, void *);
        uint64 t (*hash) (void *);
        struct bucket *buckets[];
struct bucket {
        void *key;
        void *value;
        struct bucket *next;
```

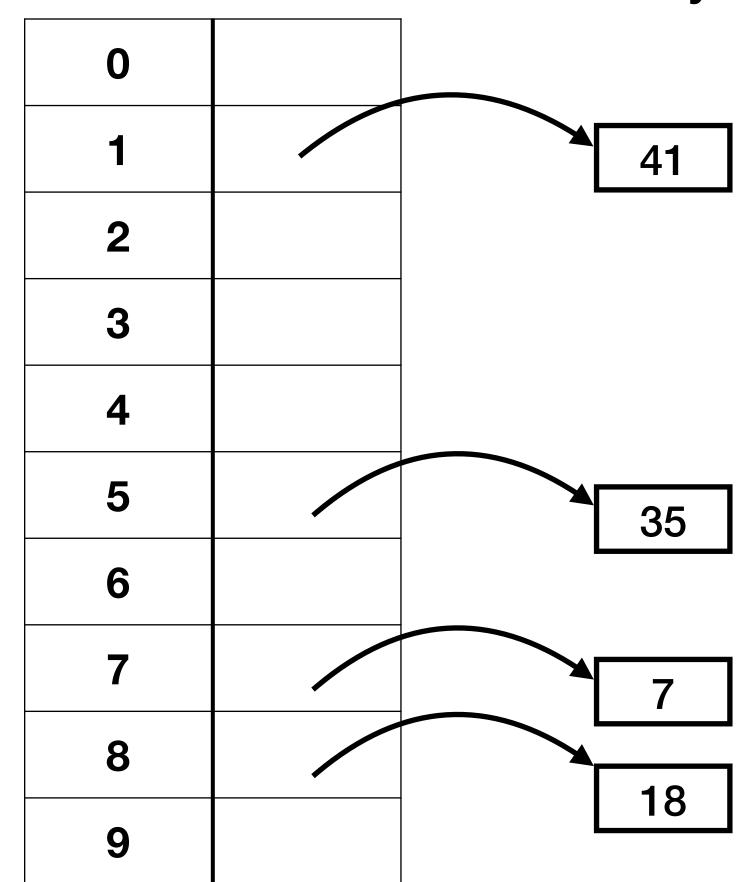
Insert



```
struct table {
        int size;
        int length;
        int (*eq) (void *, void *);
        uint64 t (*hash) (void *);
        struct bucket *buckets[];
struct bucket {
        void *key;
        void *value;
        struct bucket *next;
```

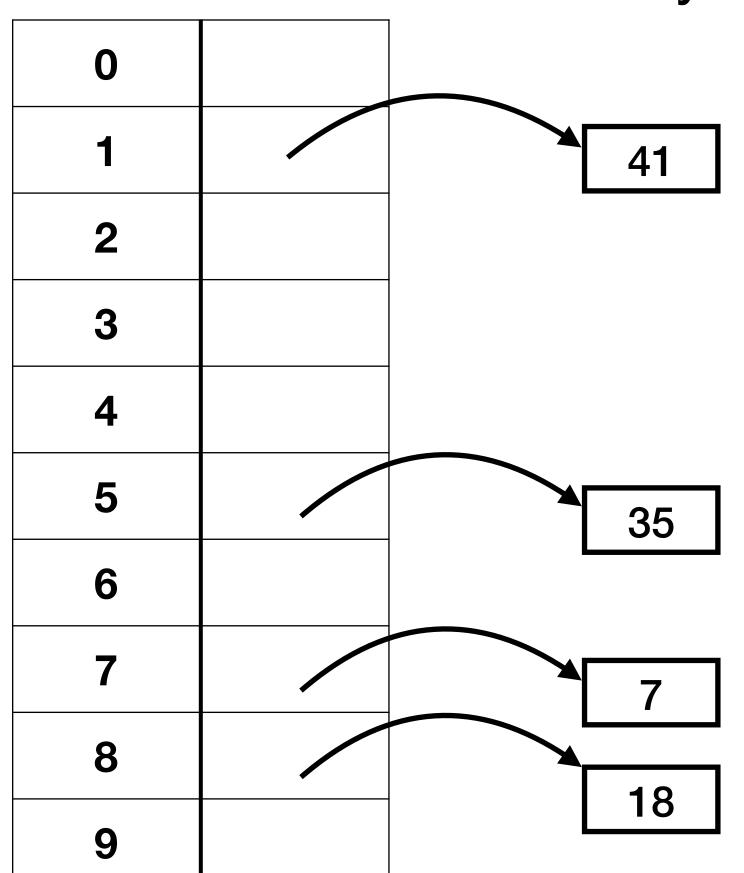
Insert

• Each slot is a *list* of key-value pairs, called a *bucket*



Insert

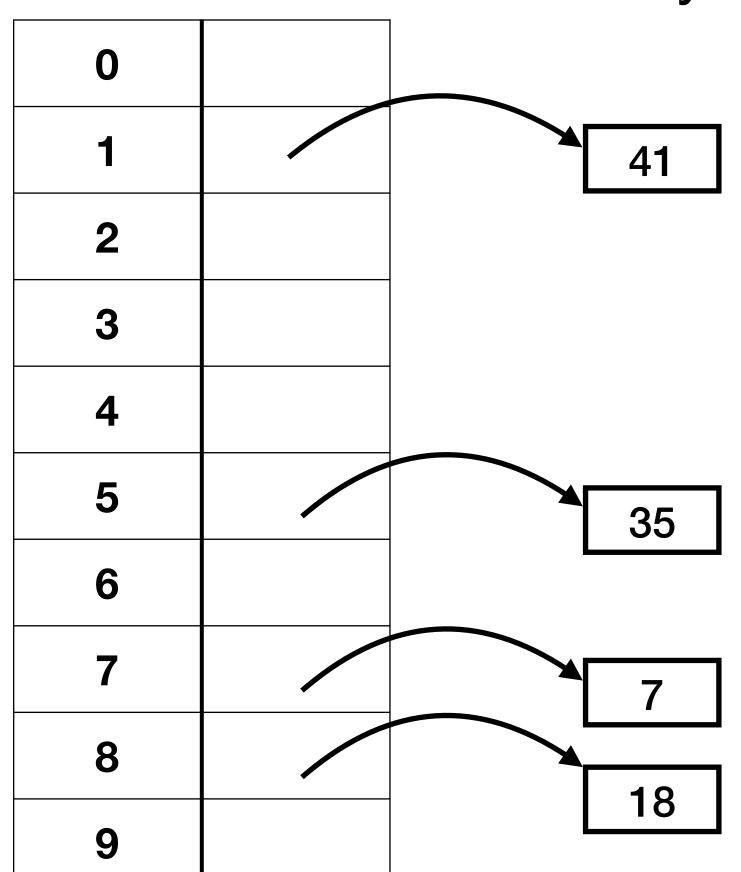
• Each slot is a *list* of key-value pairs, called a bucket



struct table {

Insert

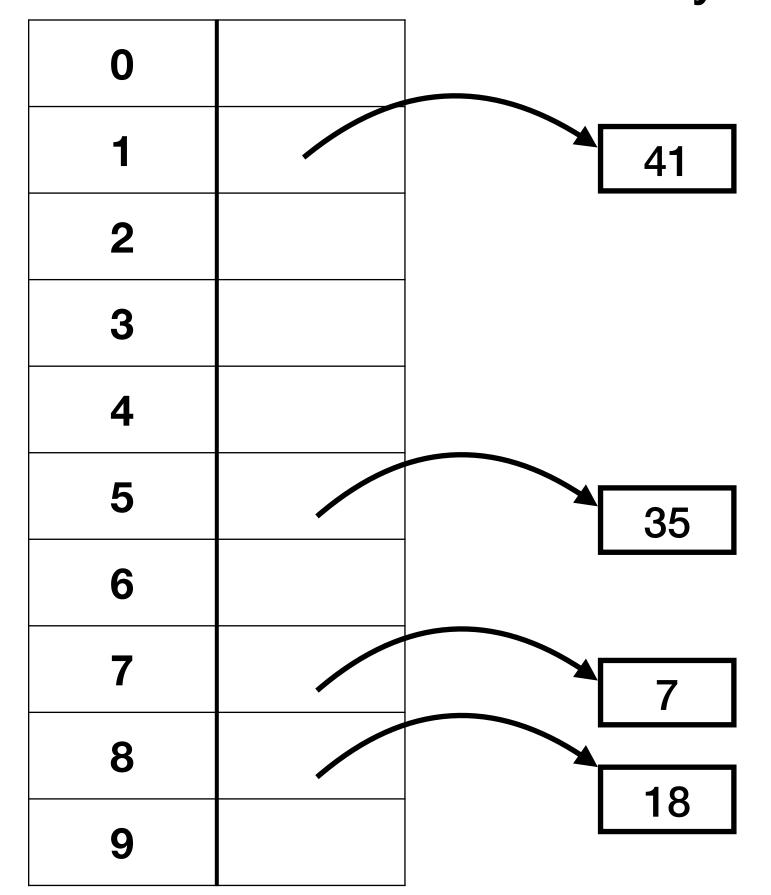
• Each slot is a *list* of key-value pairs, called a *bucket*



```
struct table {
   int size;
```

Insert

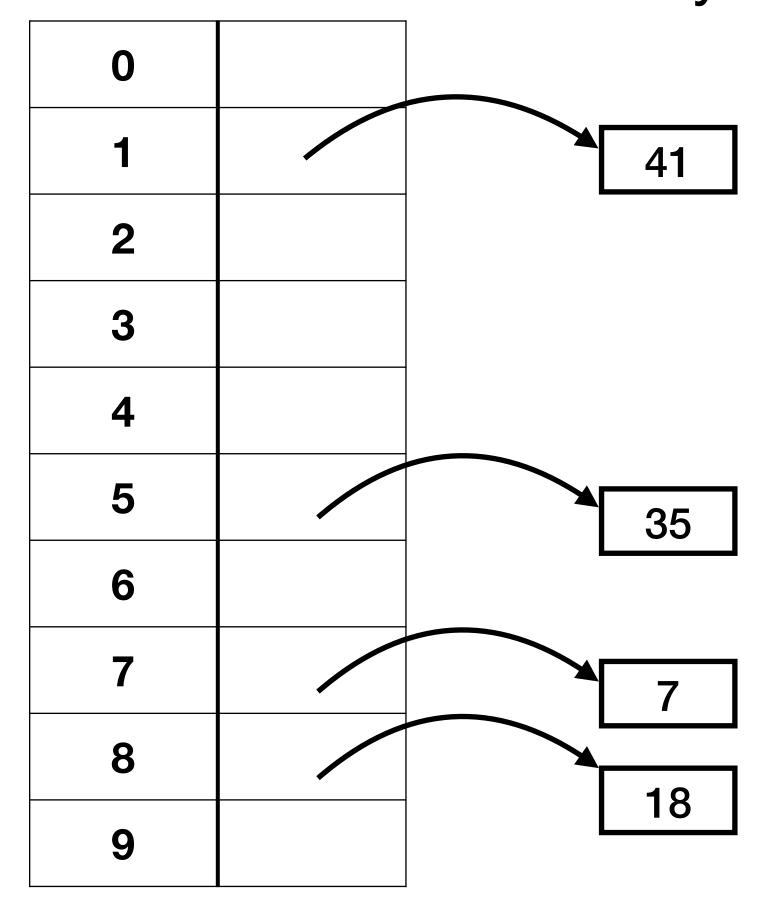
• Each slot is a *list* of key-value pairs, called a *bucket*



```
struct table {
   int size;
   int length;
```

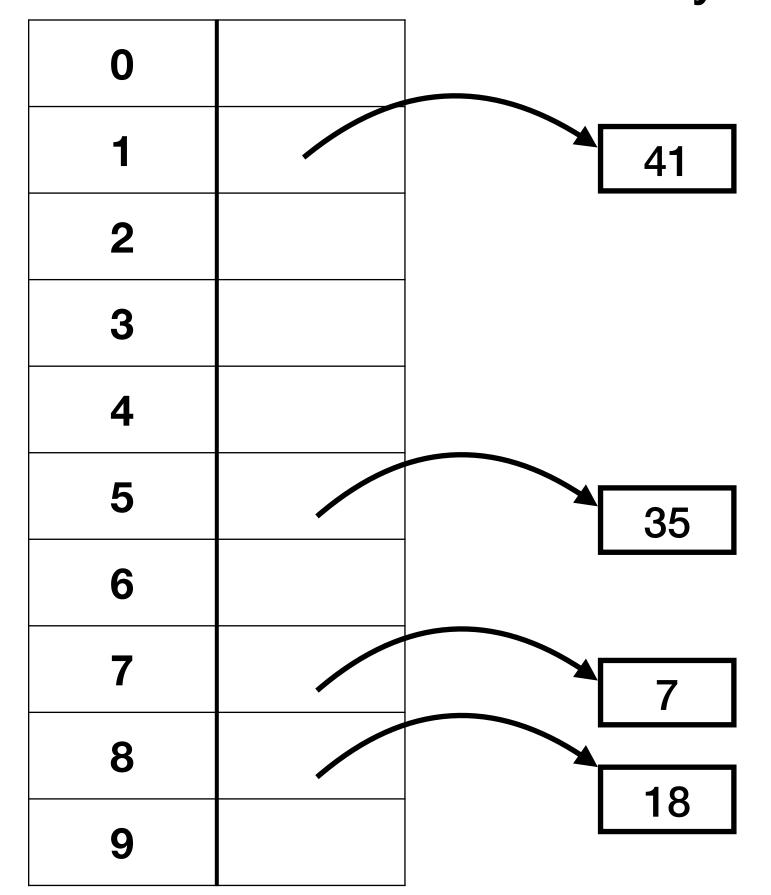
Insert

• Each slot is a *list* of key-value pairs, called a *bucket*



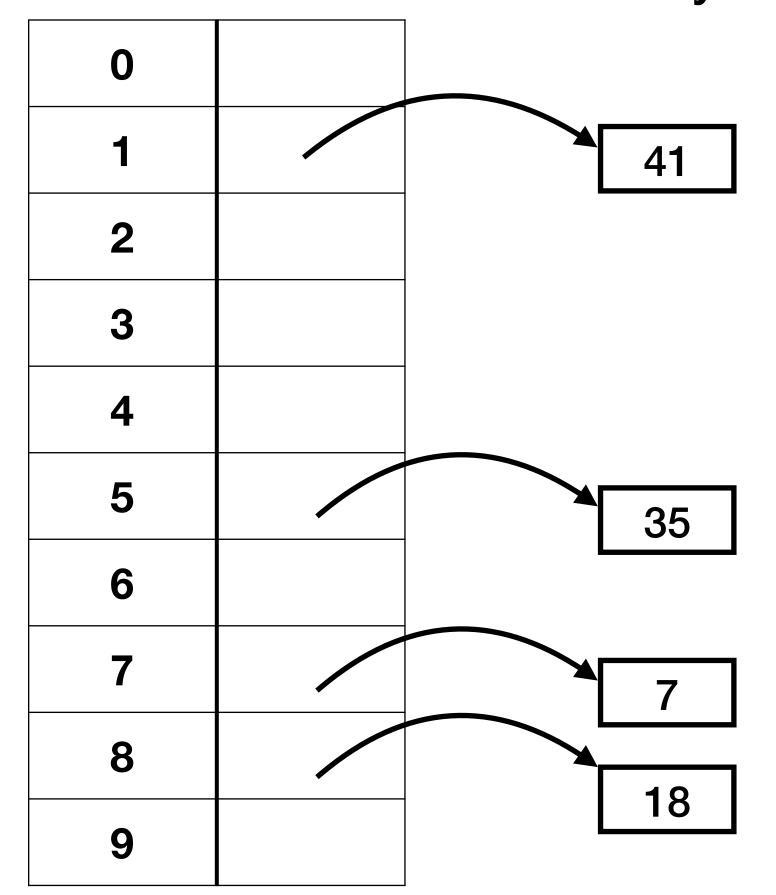
```
struct table {
   int size;
   int length;
   int (*eq)(void *, void *);
```

Insert



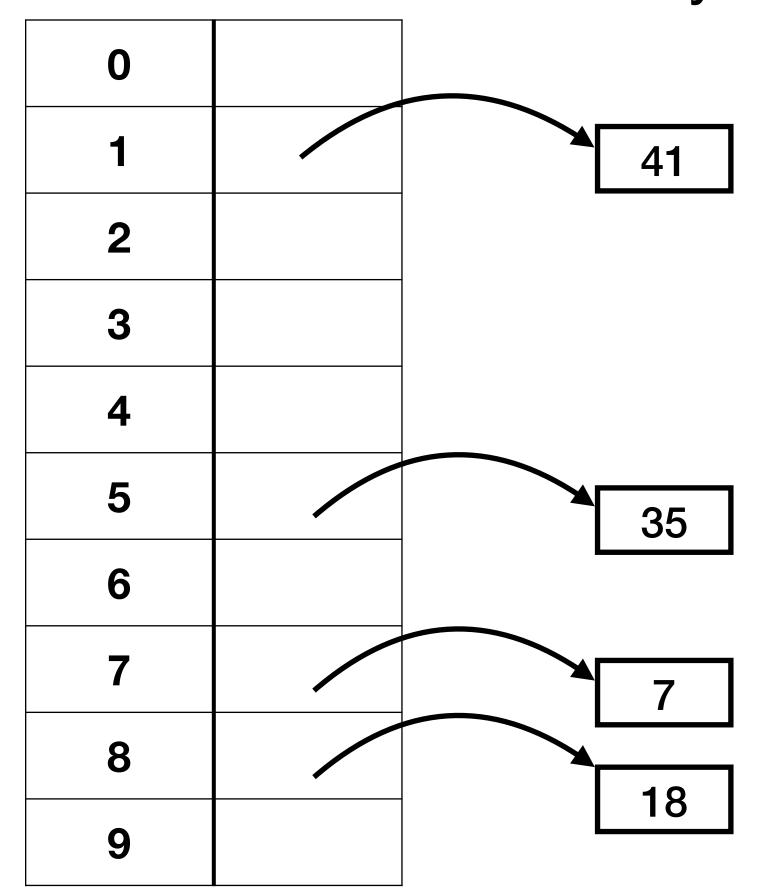
```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    <-- what is this?</pre>
```

Insert



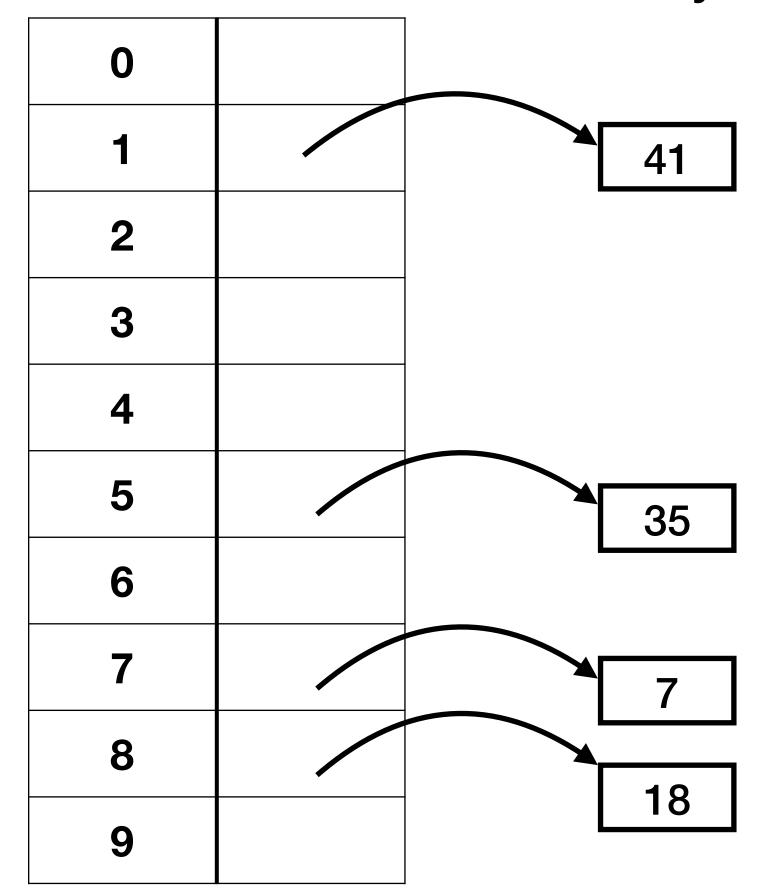
```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[]; <<-- what is this?</pre>
```

Insert



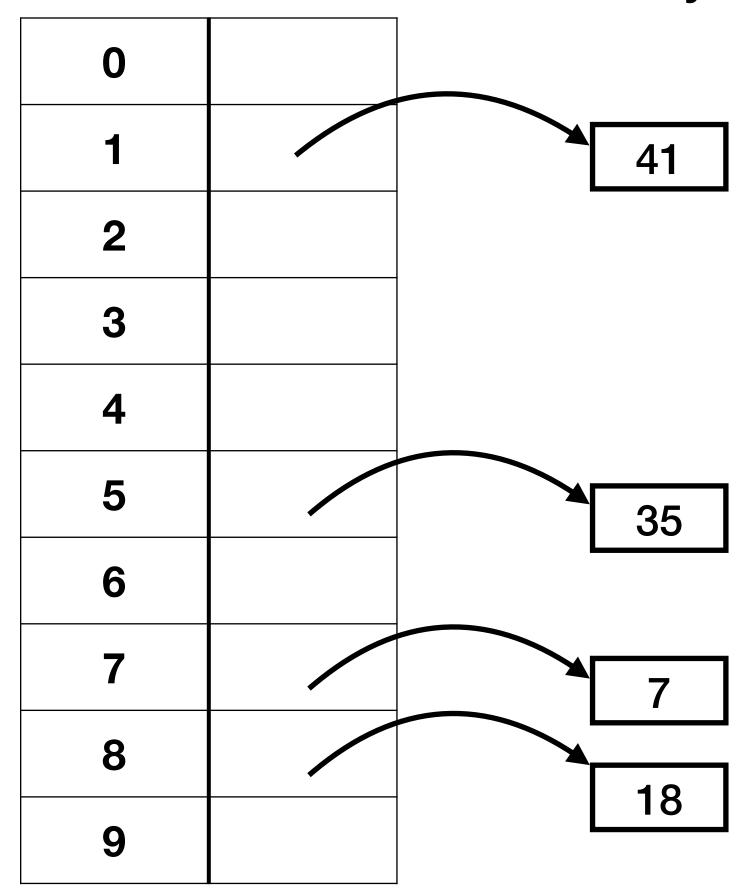
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struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[]; <<-- what is this?
};</pre>
```

Insert



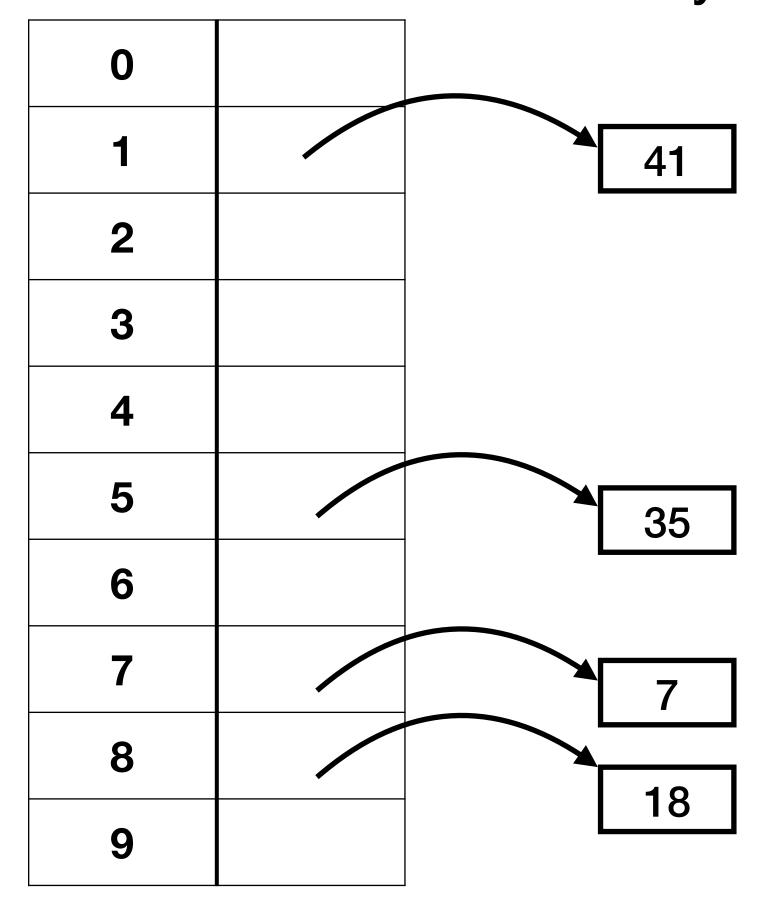
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    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
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Insert



```
struct table {
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    int length;
    int (*eq) (void *, void *);
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    struct bucket *buckets[]; <<-- what is this?
};</pre>
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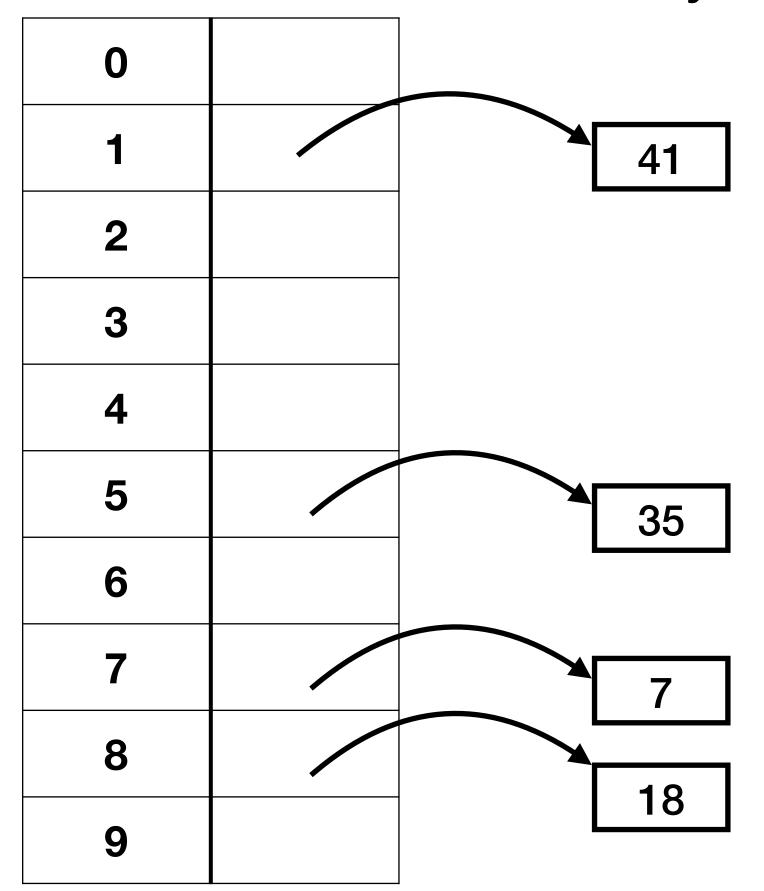
Insert



```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[]; <<-- what is this?
};

struct bucket {
    void *key;</pre>
```

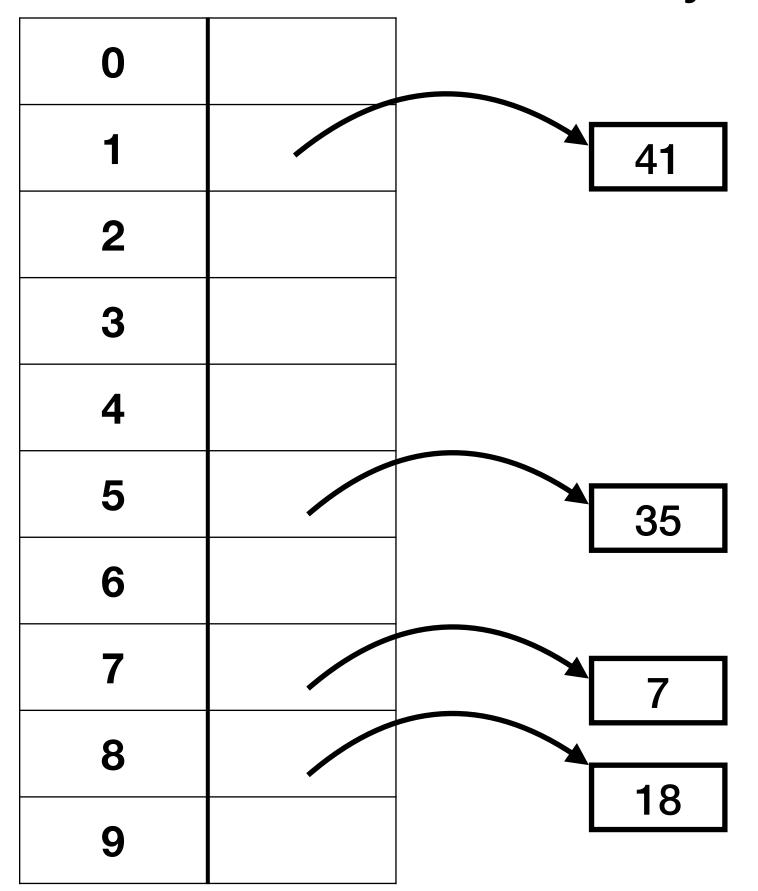
Insert



```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[]; <<-- what is this?
};

struct bucket {
    void *key;
    void *value;</pre>
```

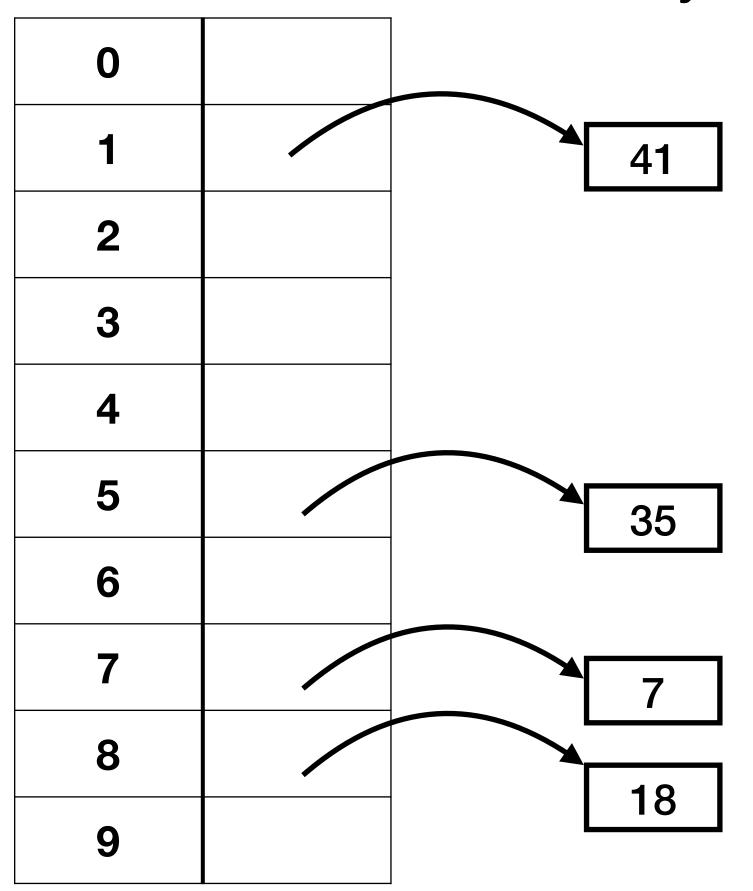
Insert



```
struct table {
    int size;
    int length;
    int (*eq) (void *, void *);
    uint64_t (*hash) (void *);
    struct bucket *buckets[]; <<-- what is this?
};

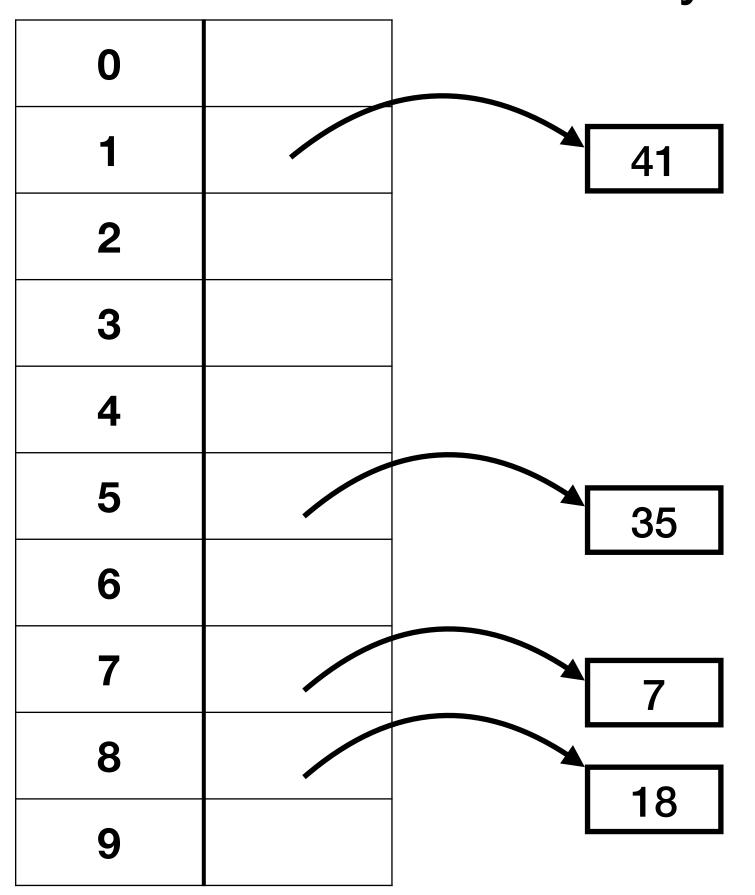
struct bucket {
    void *key;
    void *value;
    struct bucket *next;</pre>
```

Insert



```
struct table {
        int size;
        int length;
        int (*eq) (void *, void *);
        uint64 t (*hash) (void *);
         struct bucket *buckets[]; <<-- what is this?</pre>
struct bucket {
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        void *value;
         struct bucket *next;
```

Insert



```
struct table {
        int size;
        int length;
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        void *value;
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```

Interlude

Flexible array member

- The last element of a structure may have an incomplete array type (empty bracket)
- sizeof does not include the incomplete field
- Why?

```
struct table {
    int size;
    int length;
    struct bucket **buckets;
};
```

```
struct table {
    int size;
    int length;
    struct bucket *buckets[];
};
```

```
struct table {
          int size;
          int length;
          struct bucket **buckets;
};
                    table
       .size
                     int
     .length
                     int
    .buckets
                 struct bucket **
```

```
struct table {
    int size;
    int length;
    struct bucket *buckets[];
};
```

```
struct table {
          int size;
          int length;
          struct bucket **buckets;
};
                    table
       .size
                     int
     .length
                     int
    .buckets
                 struct bucket **
```

```
struct table {
         int size;
         int length;
         struct bucket *buckets[];
};
                    table
        .size
                     int
      .length
                     int
     .buckets
```

```
struct table {
             int size;
             int length;
             struct bucket **buckets;
  };
               table
  .size
                int
.length
                int
.buckets
            struct bucket **
```

```
struct table {
         int size;
         int length;
         struct bucket *buckets[];
};
              table
  .size
               int
 .length
               int
.buckets
```

```
struct table {
             int size;
             int length;
             struct bucket **buckets;
  };
               table
  .size
                int
.length
                int
.buckets
            struct bucket **
```

```
struct table {
         int size;
         int length;
         struct bucket *buckets[];
};
              table
  .size
               int
 .length
               int
.buckets
```

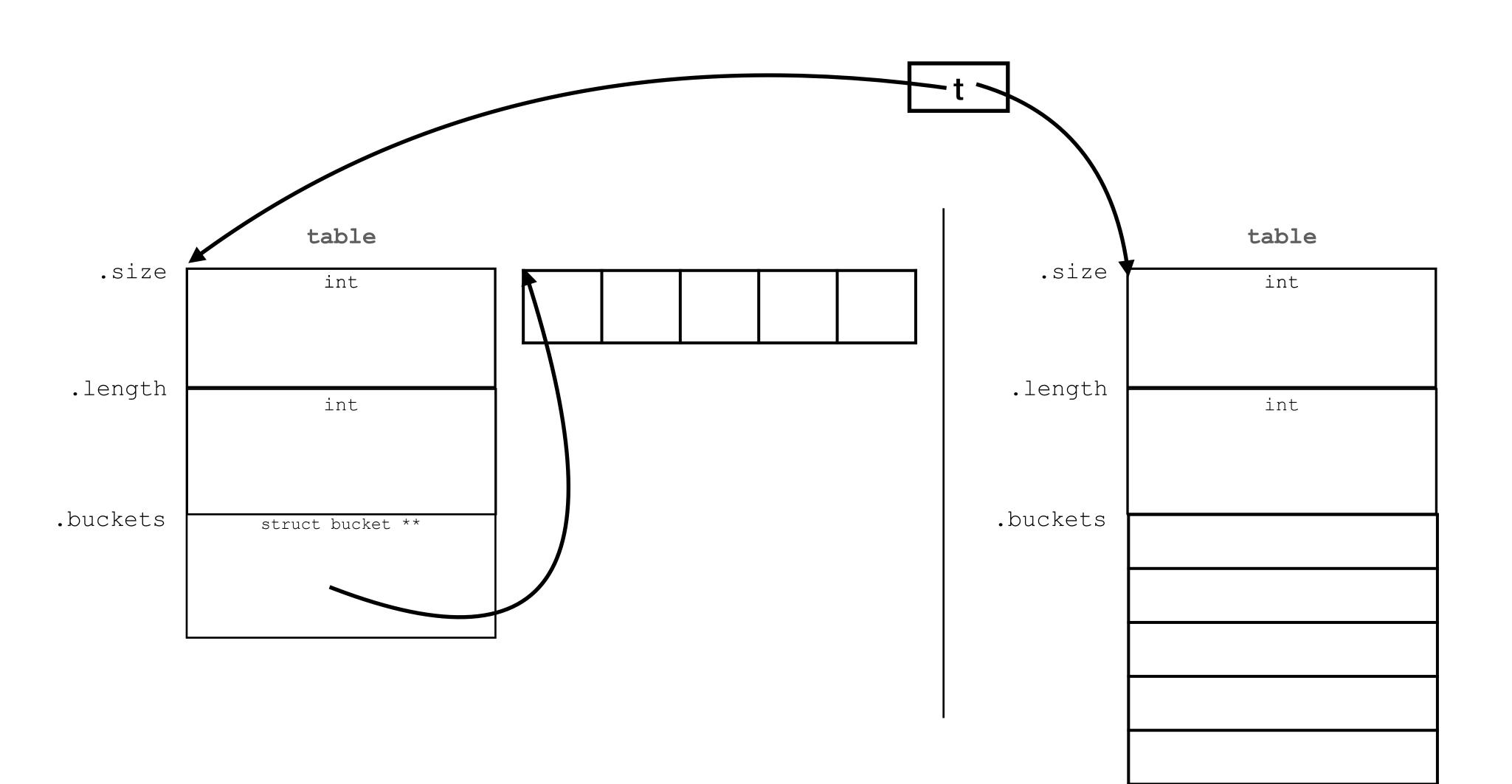
```
struct table {
             int size;
             int length;
             struct bucket **buckets;
  };
               table
  .size
                int
.length
                int
.buckets
            struct bucket **
```

```
struct table {
         int size;
         int length;
         struct bucket *buckets[];
};
              table
  .size
               int
 .length
               int
.buckets
```

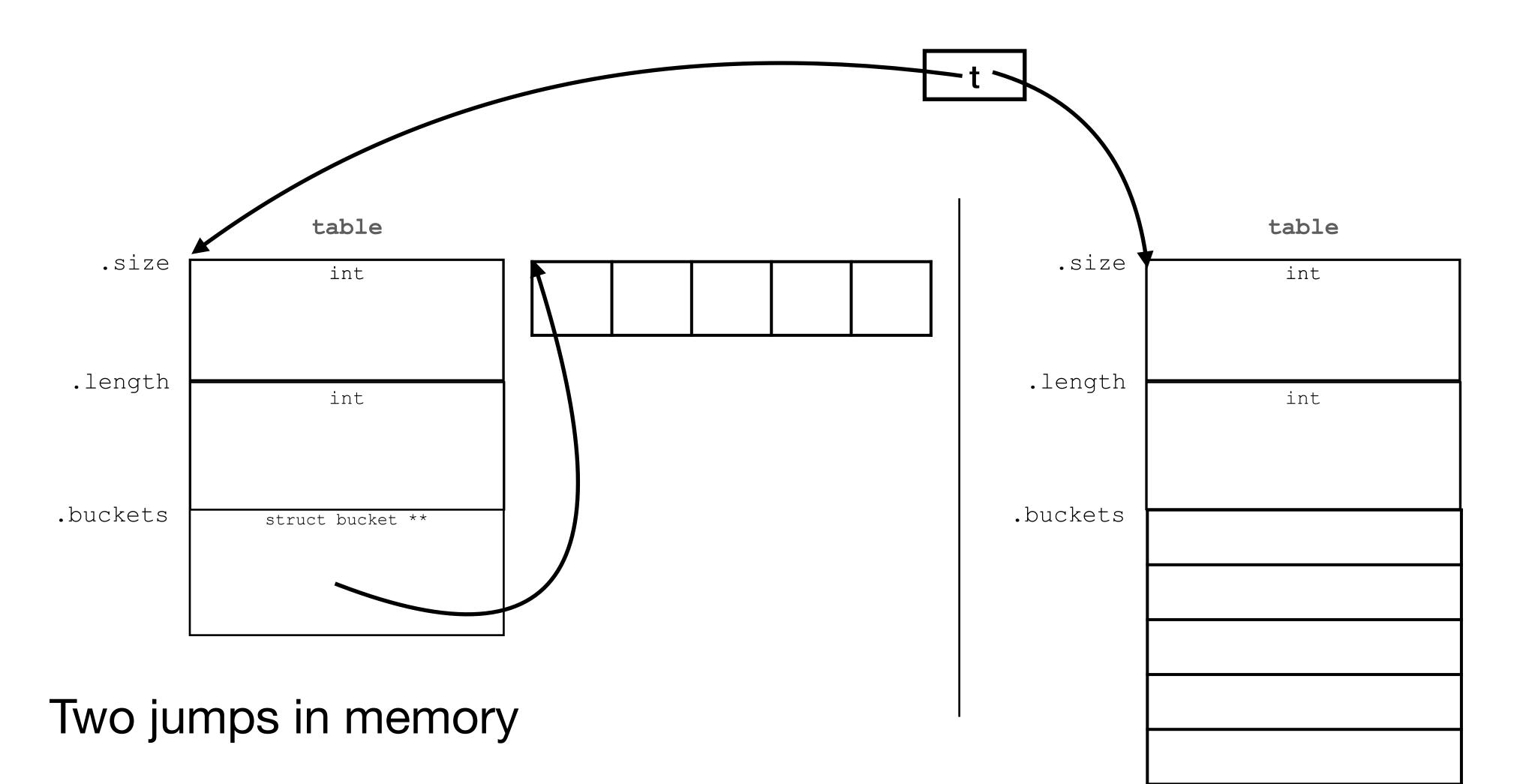
Allocation

```
struct table {
        int size;
        int length;
        struct bucket **buckets;
};
int size = 1024;
struct table *t =
  malloc(sizeof(struct table));
t->buckets =
  malloc(size * sizeof(struct bucket*));
```

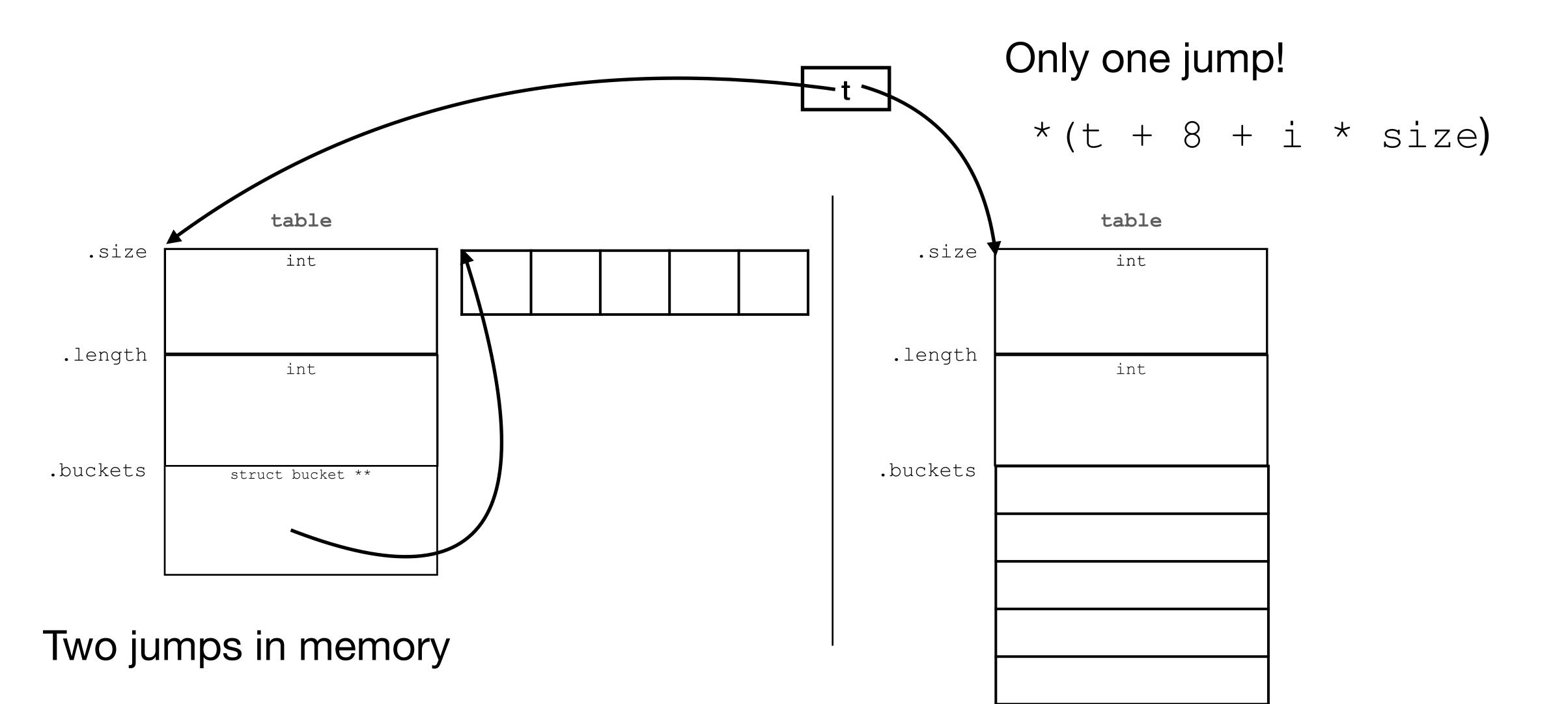
Accessing t->buckets[3];



Accessing t->buckets[3];



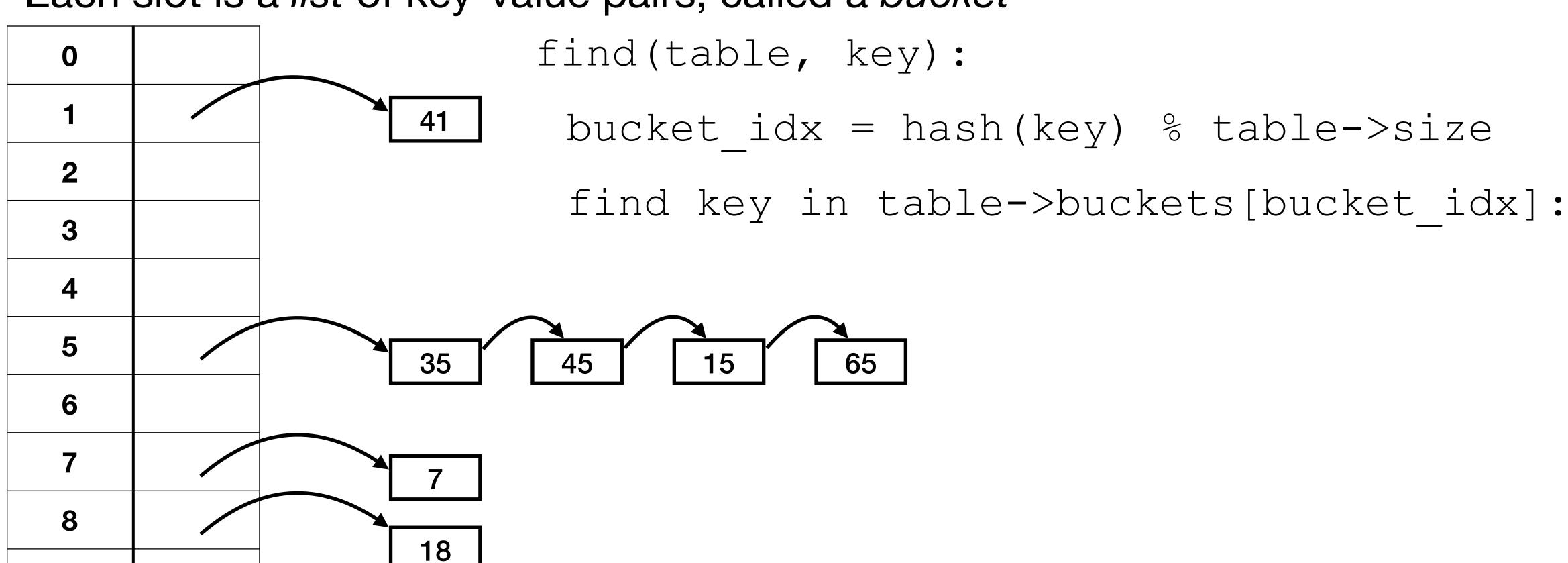
Accessing t->buckets[3];



- The last element of a structure may have an incomplete array type (empty bracket)
- sizeof does not include the incomplete field
- struct table *ptr = malloc(sizeof(struct table) + extra);
- Slight performance boost

Insert

9



Time Complexity

What is complexity for accessing elements?

- What is complexity for accessing elements?
 - O(length of the chain)

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 - What is the average (expected) length of a chain?

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- What if we have a good hash function (that has uniform distribution over a range of integers)?
 - What is the average (expected) length of a chain?

•
$$O\left(\frac{\text{\#elements}}{\text{\#buckets}}\right)$$
: this ratio is called *load factor*.

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 - Typically faster than BSTs
- Especially we can keep the load factor O(1)
 - Analysis deferred to algorithms

Hash Table

Handling Collision

- Two approaches:
 - 1. Chaining: put a list in each bucket
 - 2. Probing: use spare space in the array

0	
1	41
2	
3	
4	
5	35
6	
7	7
8	18
9	

0		
1	41	
2		
3		
4		
5	35	75
6		
7	7	
8	18	
Q		

0	
1	41
2	
3	
4	
5	35
6	75
7	7
8	18
9	

• If the bucket is occupied, use the next one.

0	
1	41
2	
3	
4	
5	35
6	75
7	7
8	18
9	

• Wrap around when reaching the end of array

	DUCKC
0	
1	41
2	
3	
4	
5	35
6	75
7	7
8	18

- Wrap around when reaching the end of array
- The table *must* have some extra space, i.e. load factor has to be ≤ 1

	DUCKC
0	
1	41
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- Many flavors of "next one":

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0	
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 - Linear probing: +1 at a time

0	
1	41
2	
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0	

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- Many flavors of "next one":
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 - Quadratic probing: * 2 at a time

11 (110	
0	
1	41
2	
3	
4	
5	35
6	75
7	7
8	18

- Wrap around when reaching the end of array
- The table must have some extra space, i.e. load factor has to be ≤ 1
- Many flavors of "next one":
 - Linear probing: +1 at a time
 - Quadratic probing: * 2 at a time
 - ...

Linear probing (example)

• Let's use strlen as our (bad) hash function

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

• insert("alice", 400)

```
struct bucket {
    void *key;
    void *value;
};
```

Linear probing (example)

• Let's use strlen as our (bad) hash function

0	
1	
2	
3	
4	
5	("alice", 400)
6	
7	
8	

insert("bob", 30)

```
struct bucket {
    void *key;
    void *value;
};
```

Linear probing (example)

• Let's use strlen as our (bad) hash function

0	
1	
2	
3	("bob", 30)
4	
5	("alice", 400)
6	
7	
8	
9	

insert("carl", 50)

```
struct bucket {
    void *key;
    void *value;
};
```

Linear probing (example)

• Let's use strlen as our (bad) hash function

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	("alice", 400)
6	
7	
8	
9	

insert("eve", 100)

```
struct bucket {
    void *key;
    void *value;
};
```

Linear probing (example)

• Let's use strlen as our (bad) hash function

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	("alice", 400)
6	("eve", 100)
7	("david", 60)
8	
9	

• insert("david", 60)

```
struct bucket {
    void *key;
    void *value;
};
```

Linear probing (example)

struct bucket {
 void *key;
 void *value;
};

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	("alice", 400)
6	("eve", 100)
7	("david", 60)
8	
9	

- find("eve")
 - Go to 3 bucket
 - Move down until we find "eve" or until we hit empty bucket
- return 100

Linear probing (example)

struct bucket {
 void *key;
 void *value;
};

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	("alice", 400)
6	("eve", 100)
7	("david", 60)
8	
9	

- find("karl")
 - Go to 4 bucket
 - Move down until we find "karl" or until we hit empty bucket
- No "karl" in table

Linear probing (example)

struct bucket {
 void *key;
 void *value;
};

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	("alice", 400)
6	("eve", 100)
7	("david", 60)
8	
9	

- remove("alice")
 - Go to 5
 - Move down until we find "alice"

Linear probing (example)

struct bucket {
 void *key;
 void *value;
};

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

- remove("alice")
 - Go to 5
 - Move down until we find "alice"

Linear probing (example)

struct bucket {
 void *key;
 void *value;
};

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

- Find("eve")
 - Go to 3
 - How far do we move down?

Linear probing (example)

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

```
struct bucket {
    void *key;
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```

Linear probing (example)

```
struct bucket {
    void *key;
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```

• Let's use strlen as our (bad) hash function

0	
1	
2	
3	("bob", 30)
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6	("eve", 100)
7	("david", 60)
8	
9	

• When we removed "alice" we left a hole

Linear probing (example)

struct bucket {
 void *key;
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};

0	
1	
2	
3	("bob", 30)
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5	
6	("eve", 100)
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8	
9	

- When we removed "alice" we left a hole
- When searching for "eve" if we stop at the hole, we won't find "eve"

Linear probing (example)

```
struct bucket {
    void *key;
    void *value;
};
```

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

- When we removed "alice" we left a hole
- When searching for "eve" if we stop at the hole, we won't find "eve"
- But if we don't stop at empty spots, we have to search through the entire array if a key doesn't exist

Linear probing (example)

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

```
struct bucket {
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Linear probing (example)

```
struct bucket {
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```

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0	
1	
2	
3	("bob", 30)
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5	
6	("eve", 100)
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8	
9	

A bucket can be in one of three states:

Linear probing (example)

```
struct bucket {
    void *key;
    void *value;
};
```

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

- A bucket can be in one of three states:
 - Occupied (key != NULL)

Linear probing (example)

struct bucket {
 void *key;
 void *value;
};

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

- A bucket can be in one of three states:
 - Occupied (key != NULL)
 - Empty, but was always empty

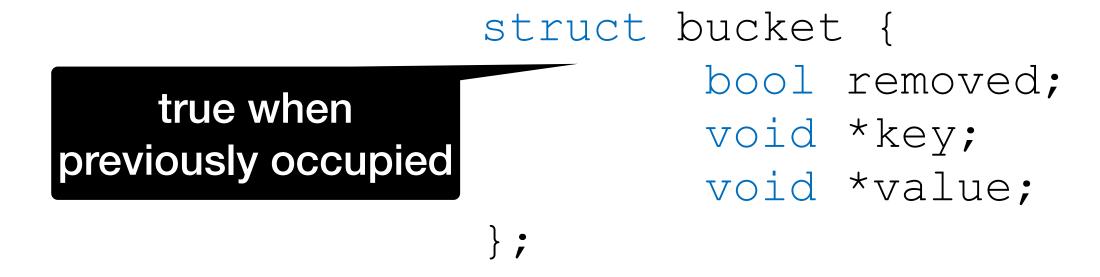
Linear probing (example)

```
struct bucket {
    void *key;
    void *value;
};
```

0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

- A bucket can be in one of three states:
 - Occupied (key != NULL)
 - Empty, but was always empty
 - Empty, but previously occupied

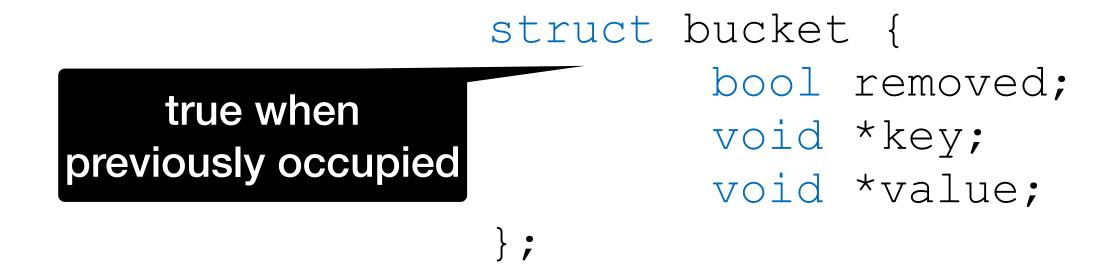
Linear probing (example)



0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	
6	("eve", 100)
7	("david", 60)
8	
9	

- A bucket can be in one of three states:
 - Occupied (key != NULL)
 - Empty, but was always empty
 - Empty, but previously occupied

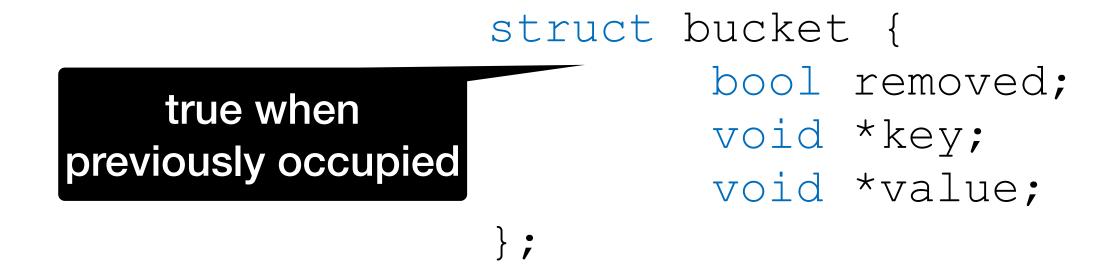
Linear probing (example)



0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	REMOVED
6	("eve", 100)
7	("david", 60)
8	
9	

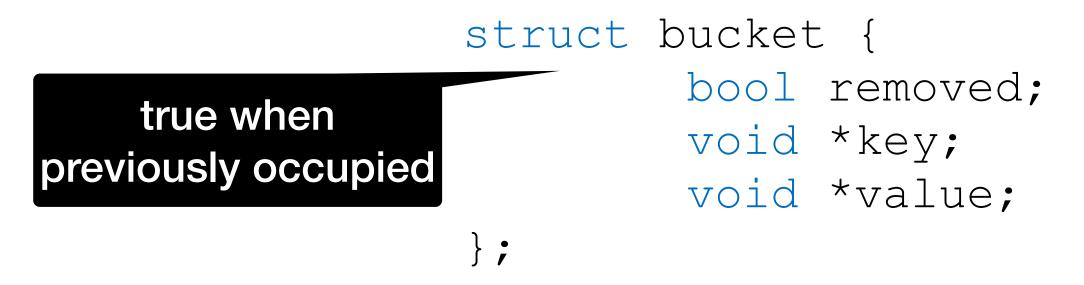
- Find("eve")
 - Go to 3
 - Move down until we find "eve", or until we hit an empty, non-removed bucket

Linear probing (example)

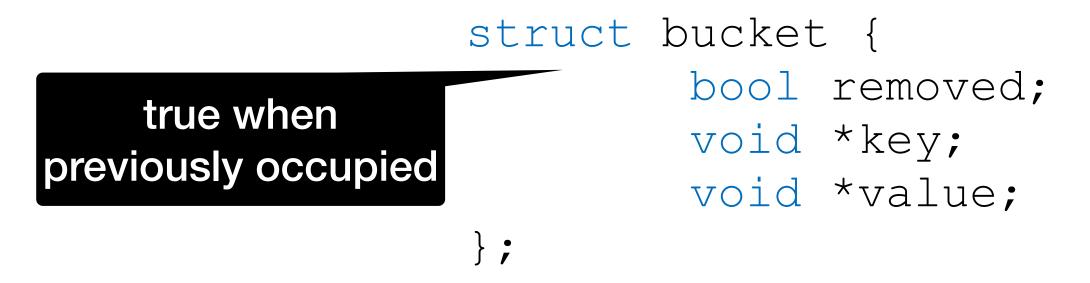


	1
0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	RIP
6	("eve", 100)
7	("david", 60)
8	
9	

- Find("eve")
 - Go to 3
 - Move down until we find "eve", or until we hit an empty, non-removed bucket
- This empty but removed bucket is sometimes called a tombstone



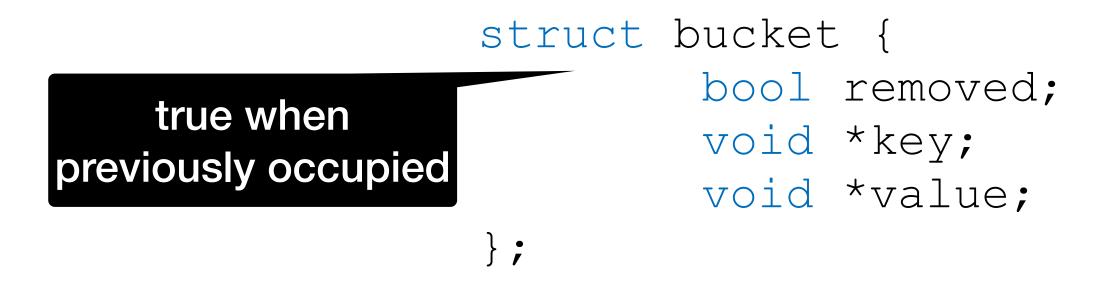
0	
1	
2	
3	("bob", 30)
4	("carl", 50)
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6	("eve", 100)
7	("david", 60)
8	
9	



• Let's use strlen as our (bad) hash function

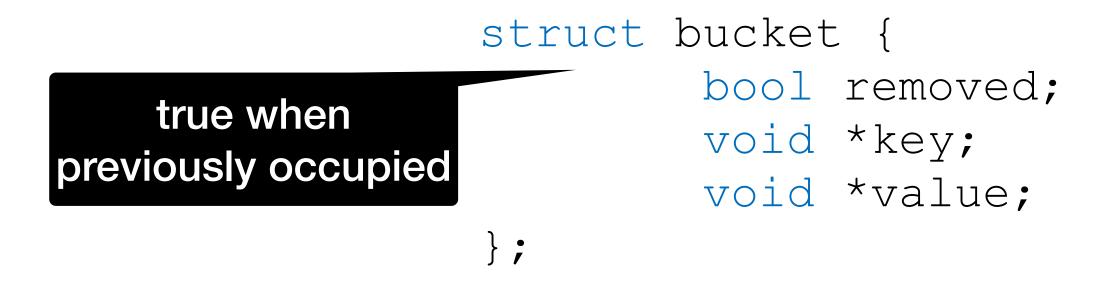
0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	RIP
6	("eve", 100)
7	("david", 60)
8	
9	

Find/Remove:



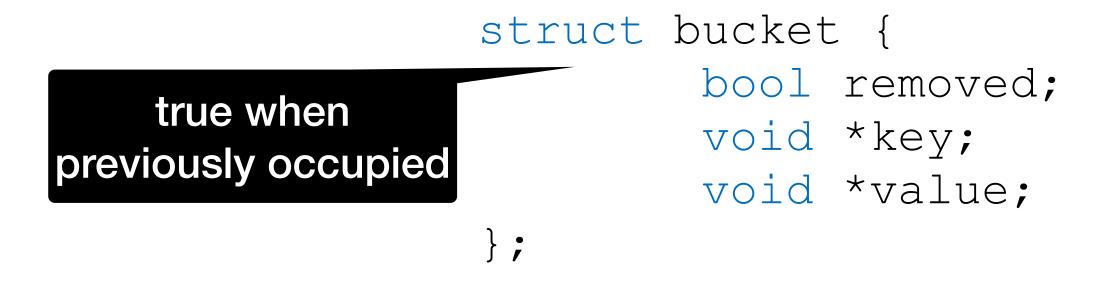
0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	RIP
6	("eve", 100)
7	("david", 60)
8	
9	

- Find/Remove:
 - Move down until first empty bucket



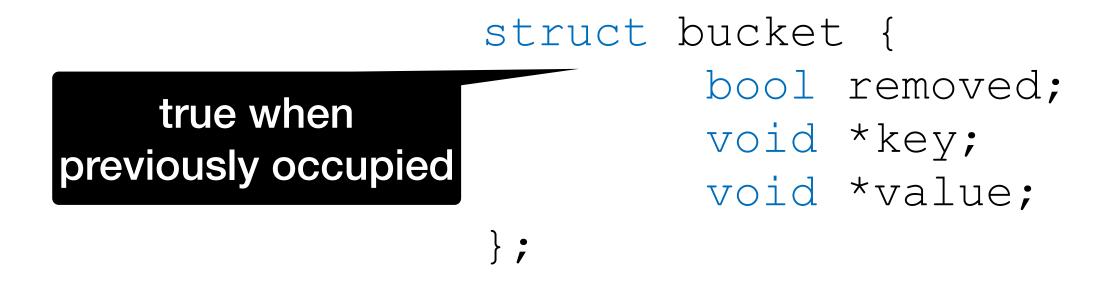
0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	RIP
6	("eve", 100)
7	("david", 60)
8	
9	

- Find/Remove:
 - Move down until first empty bucket
 - If tombstone is encountered, continue searching



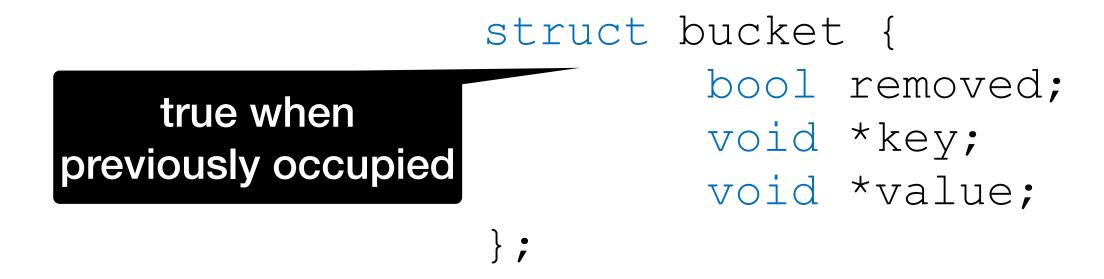
0	
1	
2	
3	("bob", 30)
4	("carl", 50)
5	RIP
6	("eve", 100)
7	("david", 60)
8	
9	

- Find/Remove:
 - Move down until first empty bucket
 - If tombstone is encountered, continue searching
- Insert:



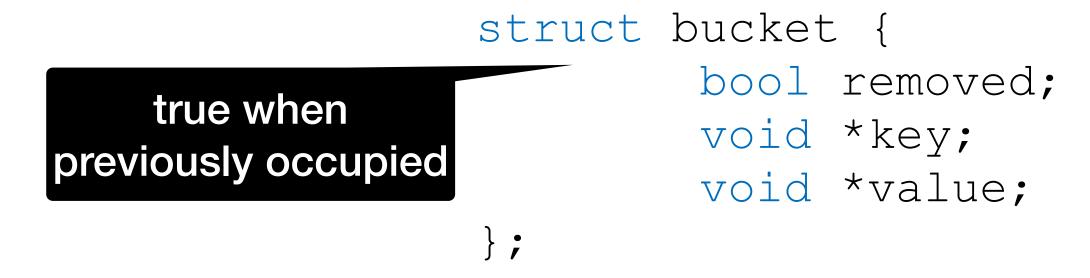
0	
1	
2	
3	("bob", 30)
4	("carl", 50)
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6	("eve", 100)
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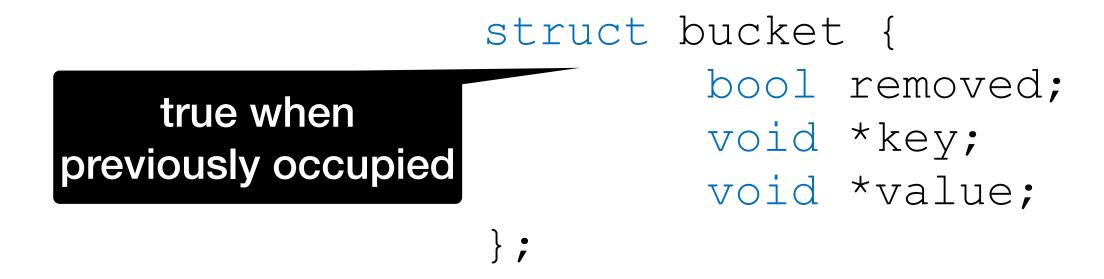
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0	
1	
2	
3	("bob", 30)
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6	("eve", 100)
7	("david", 60)
8	
9	

- Find/Remove:
 - Move down until first empty bucket
 - If tombstone is encountered, continue searching
- Insert:
 - Move down until first empty bucket
 - If tombstone is encountered, we can reuse that bucket



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1	
2	
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4	("carl", 50)
5	RIP
6	("eve", 100)
7	("david", 60)
8	
9	

- Find/Remove:
 - Move down until first empty bucket
 - If tombstone is encountered, continue searching
- Insert:
 - Move down until first empty bucket
 - If tombstone is encountered, we can reuse that bucket
 - But to avoid inserting duplicate keys, we need to continue searching until an unremoved bucket



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   void *key;
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 - Really bad for probing
 - Clusters mean we need to go through more buckets

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• Chaining: worst O(n), average O(1)

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 - Get: O(table_size)
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- On average, the number of probes is at most $1/(1 \log d factor)$

Probing Time Complexity (Appendix)

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$$= \sum_{i=0}^{\infty} load factor^{i}$$

$$= \frac{1}{1 - \text{load factor}}$$

Time Complexity (Appendix)

- Let A_i be the event that the ith probe is occupied.
 - $Pr[A_1] = n/m$, assuming n elements and m slots
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•
$$\Pr[A_1 \cap A_2 \cap ... \cap A_{i-1}] = \frac{n}{m} \cdot \frac{n-1}{m-1} ... \frac{n-i+2}{m-i+2} \le \left(\frac{n}{m}\right)^{i-1} = \text{load factor}^{i-1}$$

$$E[\# \text{probes}] = \sum_{i=1}^{\infty} \Pr[A_1 \cap \ldots \cap A_{i-1}]$$

$$\leq \sum_{i=1}^{\infty} \operatorname{load} \operatorname{factor}^{i-1}$$

$$= \sum_{i=0}^{\infty} \operatorname{load} \operatorname{factor}^{i}$$

$$= \frac{1}{1 - \text{load factor}}$$

• E.g. if the table is half full, the average number of probes is 1/(1 - 0.5) = 2

Notes

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- What should we do when we hit the maximum load factor?
 - Increase the # of buckets
 - Can we just realloc? I.e. put the same elements in the same buckets after expansion?

Maps Complexity

	lookup		insert		remove	
	average	worst	average	worst	average	worst
ArrayList	O(n)		O(1)	O(n)	O(-	1)
Linked List	O(n)		O(1)		O(1)	
ArrayList (sorted)	O(log n)		O	(n)	O(n)	
Linked List (sorted)	O(n)		O(1)		O(1)	
BST	O(log n)	O(n)	O(log n)	O(n)	O(log n)	O(n)
Hash Table	O(1)	O(n)	O(1)	O(n)	O(1)	O(n)

Epilogue

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 - Better to use a heap or BST for these
- Operations that involve ordering, insert "front" and "back"
 - Hash tables have no notion of "order" -- in C++, hash tables are called unordered_map

In one slide

- Array access is O(1).
- Using arbitrary keys as array indices:
 - Hash functions turn any values into an integer. Ideally, this should be uniform.
 - Compress function forces integers into [0, table_size).
- Handling Collision:
 - Chaining: put a list in each bucket
 - Probing: use spare space in the array
- Load factor: the expected number of elements to go through
 - #elements / #buckets
 - Chaining: load factor has no limit; probing: load factor at most 1
 - Adjusting #buckets to keep load factor (0.7 0.75) -- time/space trade-off

Data Structures

- Establishing structures on the heap:
 - Indices: contiguous
 - O(1) random access
 - difficult to reorder and reallocate
 - Pointer: scattered
 - sequential access
 - easy to reorder and reallocate

	Indices	Pointers	
List	Array List	Linked List	
Map	Hash Table	BST	